

## An Overview of the SCEC Earthquake Simulation Program and the CyberShake Project

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CyberShake co-developers: S. Callaghan, R. Graves, F. Wang, K. Olsen, K. Milner, and P. Maechling, En-Jui Lee, Po Chen

Meeting of the SCEC Committee for the Utilization of Ground Motion Simulations

12 May 2014

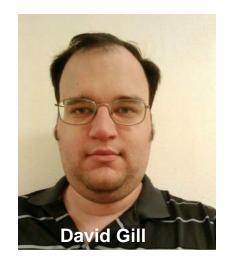


## SCEC IT/CS Staff









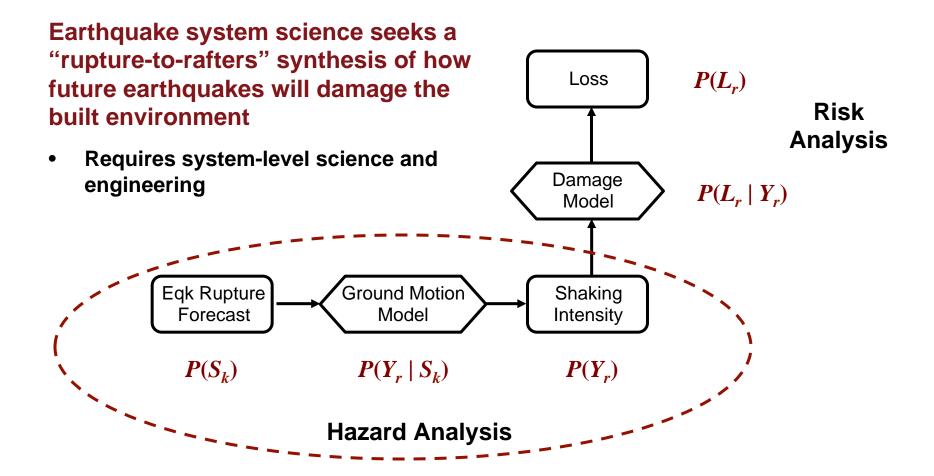








#### Earthquake System Science





#### Presentation Outline

- 1. Overview of the SCEC earthquake simulation program
- 2. Formulation of simulation-based PSHA
- 3. Introduction to the CyberShake computational platform
- 4. 3D seismic velocity structure from full-3D inversion
- 5. Comparisons Among CyberShake Models and NGA GMPE
- 6. Plans for future CyberShake reserarch

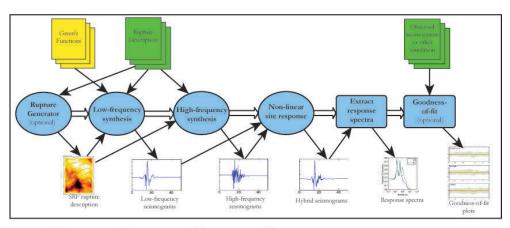


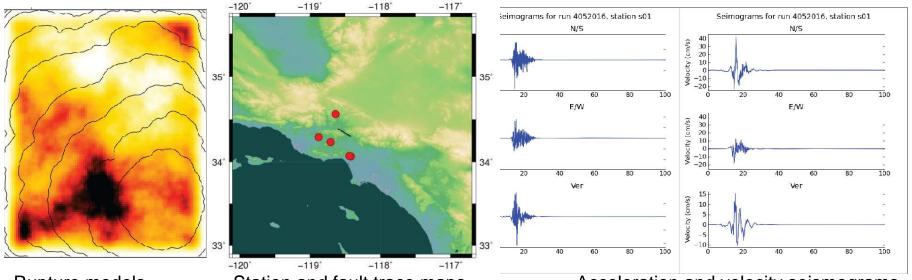
## Overview of the SCEC Earthquake Simulation Program



#### Broadband Platform

# Ground motion modeling software for frequencies from 0.0 to 10Hz, designed for flexible use by earthquake engineers





Rupture models

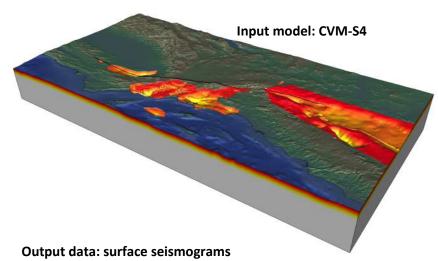
Station and fault trace maps

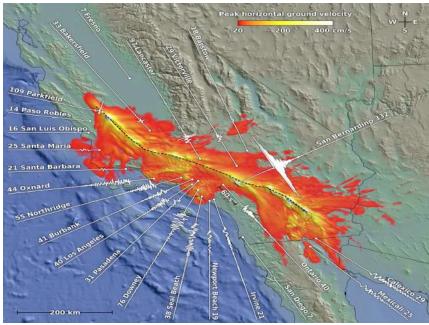
Acceleration and velocity seismograms



#### **M8 Simulation**

- Magnitude 8.0 wall-to-wall scenario, worst-case for southern San Andreas Fault
  - Fault length: 545 km
  - Minimum wavelength: 200 m
- Dynamic rupture simulation (pathway 3) performed on *Kraken*, 7.5 hours using 2160 cores
  - 881,475 subfaults, 250 sec of rupture
  - 2.1 TB tensor time series output
- Wave propagation simulation (pathway 2) performed on *Jaguar*, 24 hours using 223,074 cores (220 Tflop/s sustained).
  - 436 billion grid points representing geologic model of dimension 810 x 405 x 85 km (40-m sampling)
  - 368 s of ground motions (160,000 steps of 0.0023 s) representing seismic frequencies up to 2 Hz

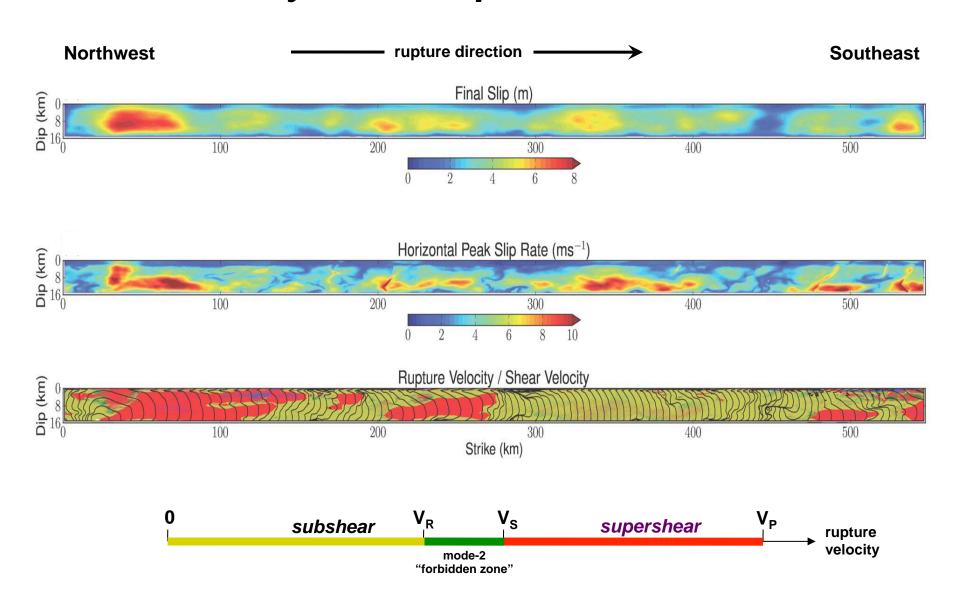




4D outer/inner scale ratio: 7 x 10<sup>16</sup>

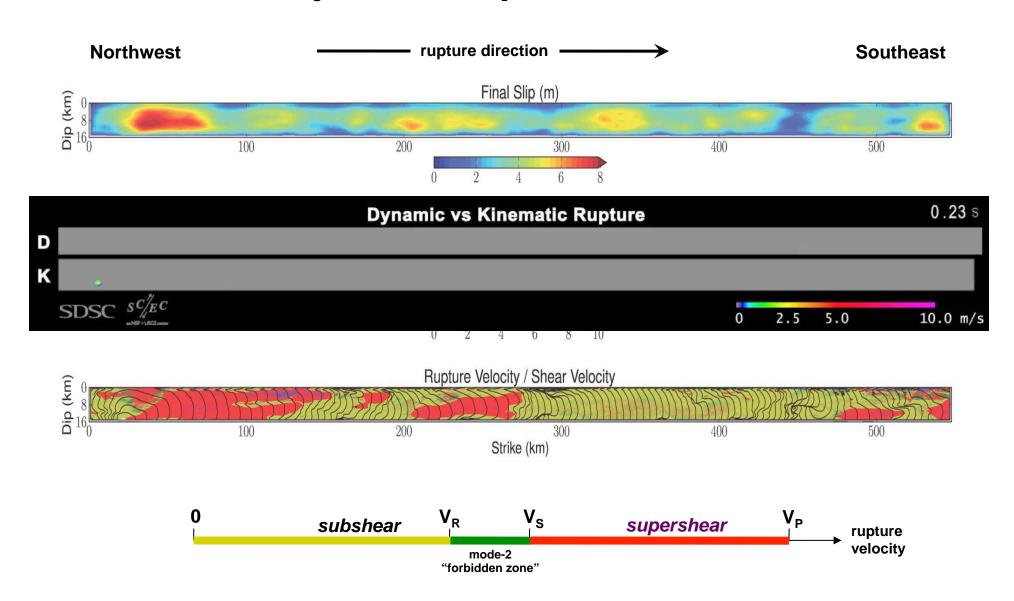


### M8 Dynamic Rupture Simulation



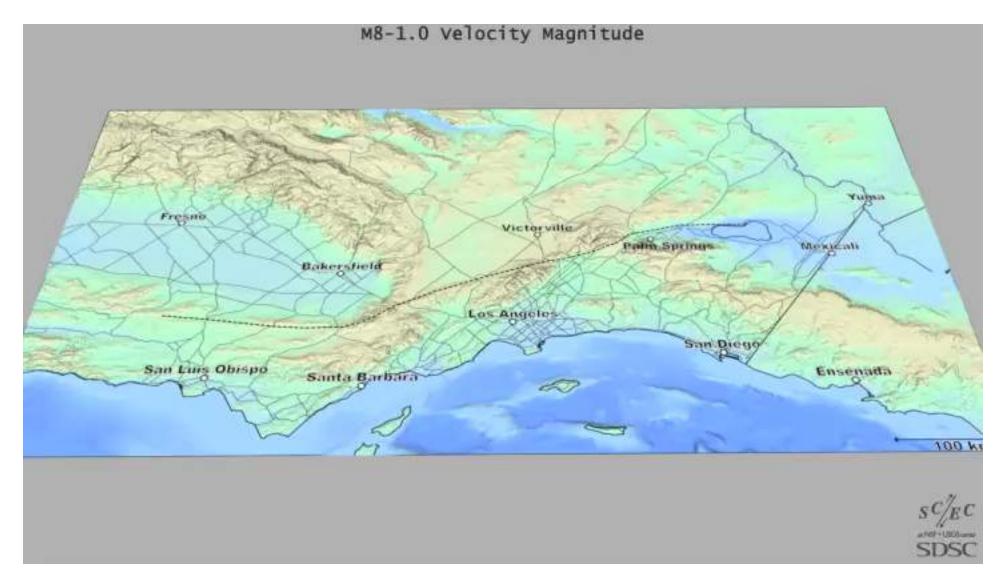


#### M8 Dynamic Rupture Simulation



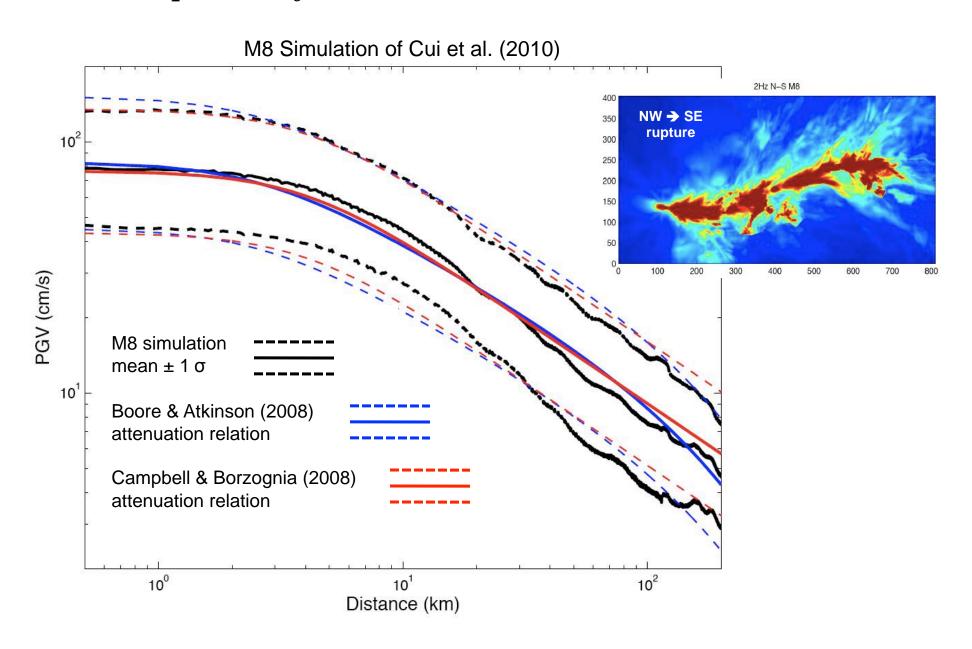


#### **M8 Ground Motion Simulation**





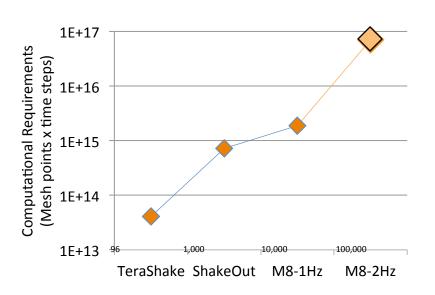
#### Comparison of M8 Ground Motions with NGA GMPEs

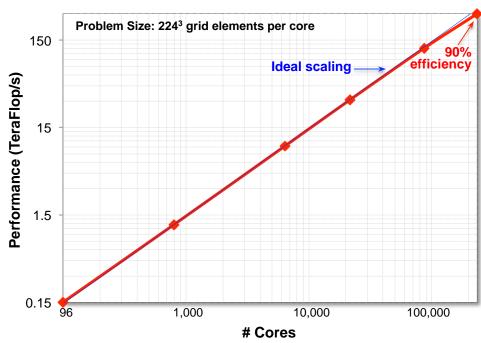




#### SCEC Large-Scale Simulations





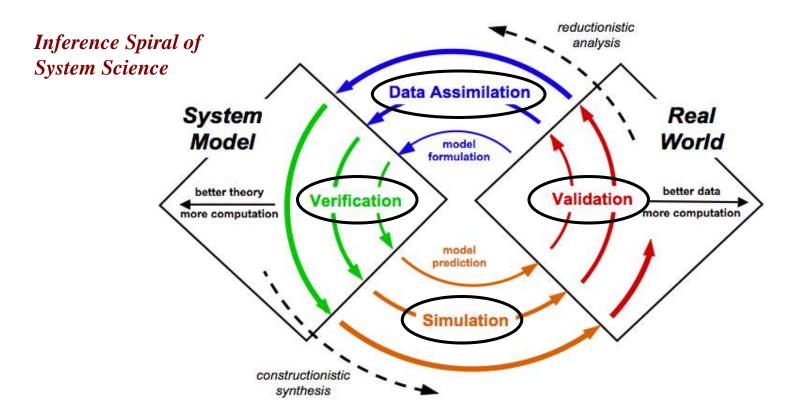


Increased computational performance has paved the way for the large suites of simulations needed for probabilistic seismic hazard analysis (PSHA)



#### Inference Spiral

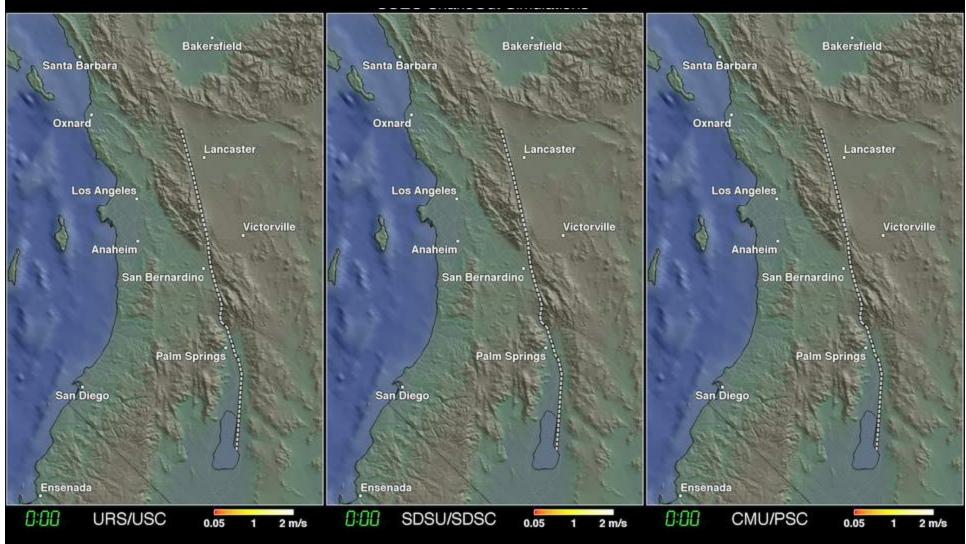
 Earthquake system science requires an iterative, computationally intense process of model formulation and verification, simulation-based predictions, validation against observations, and data assimilation to improve the model



 As models become more complex and new data bring in more information, we require ever increasing computational resources

## Cross-Verification of Simulations

SCEC ShakeOut Simulations

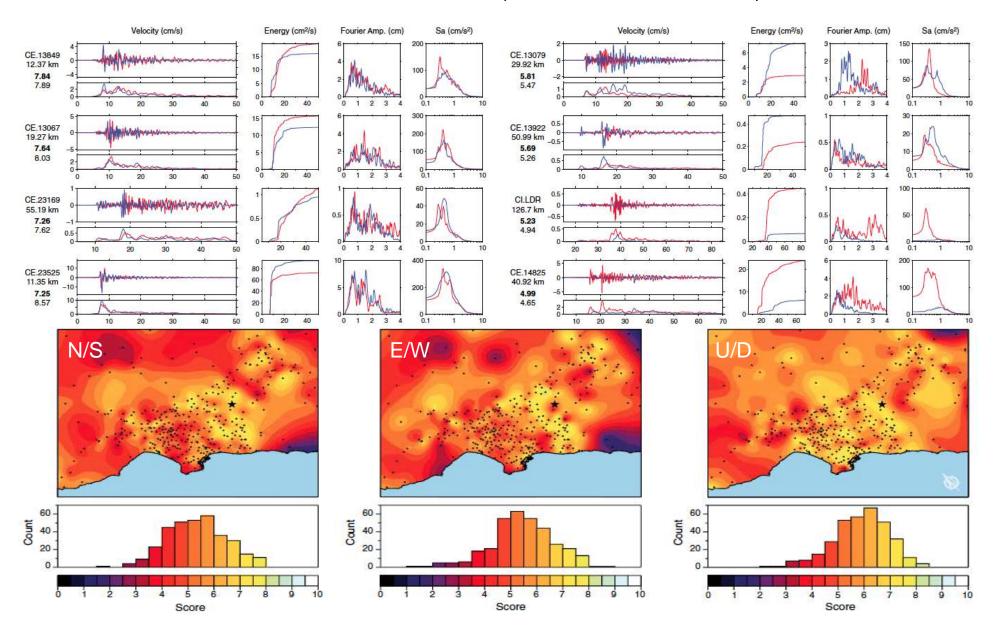


Bielak, J., R. W. Graves, K. B. Olsen, R. Taborda, L. Ramírez-Guzmán, S. M. Day, G. P. Ely, D. Roten, T. H. Jordan, P. J. Maechling, J. Urbanic, Y. Cui & G. Juve (2010)



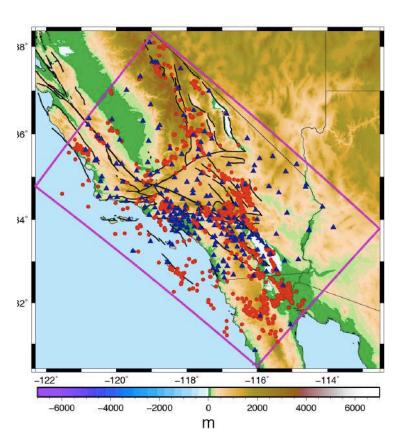
## Validation Using Small Earthquakes

2008 Chino Hills, M5.4 (Taborda & Bielak, 2013)



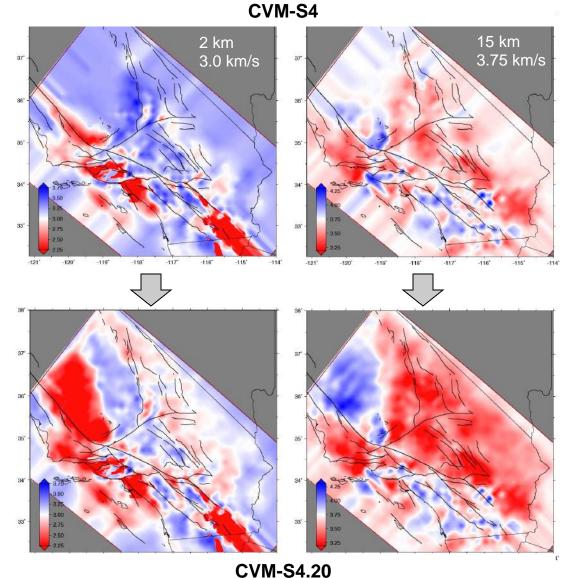


# Data Assimilation Using Full-3D Waveform Tomography



E.-J. Lee, P. Chen, T. H. Jordan, P. Maechling, M. Denolle, G. Beroza (2012)

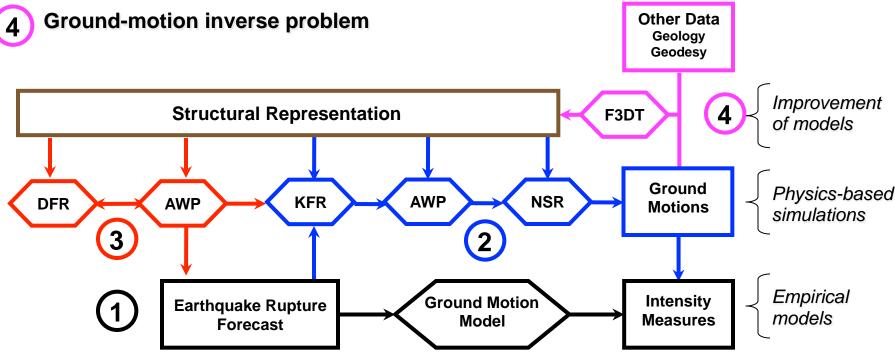
Inversion of Earthquake Waveforms and Ambient-Noise Green Functions





- Earthquake rupture forecasting
- **Ground motion simulation**
- **Dynamic rupture modeling**

## SCEC Computational **Pathways**



**KFR = Kinematic Fault Rupture** 

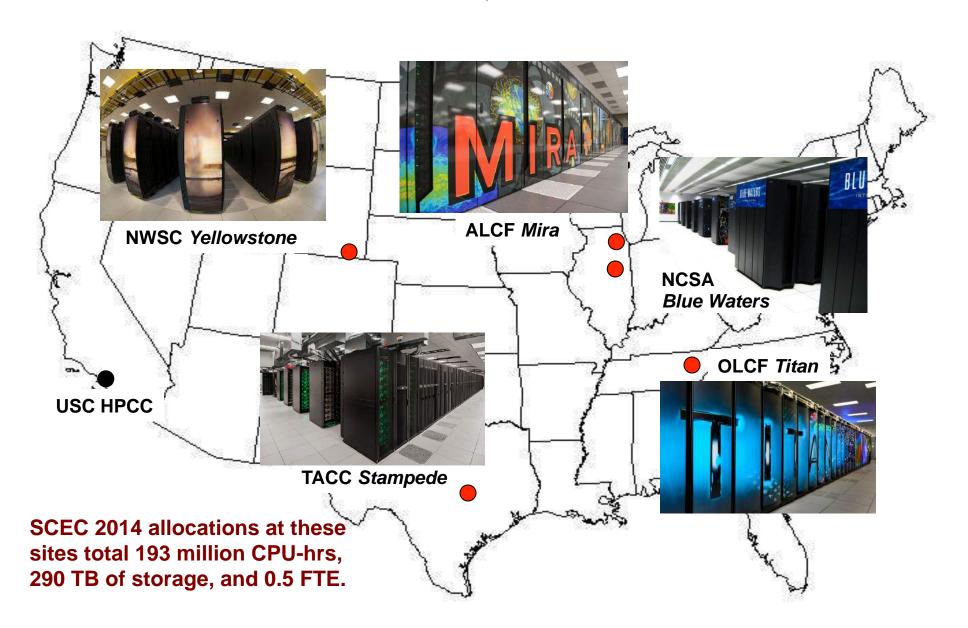
**DFR = Dynamic Fault Rupture** 

**AWP = Anelastic Wave Propagation** 

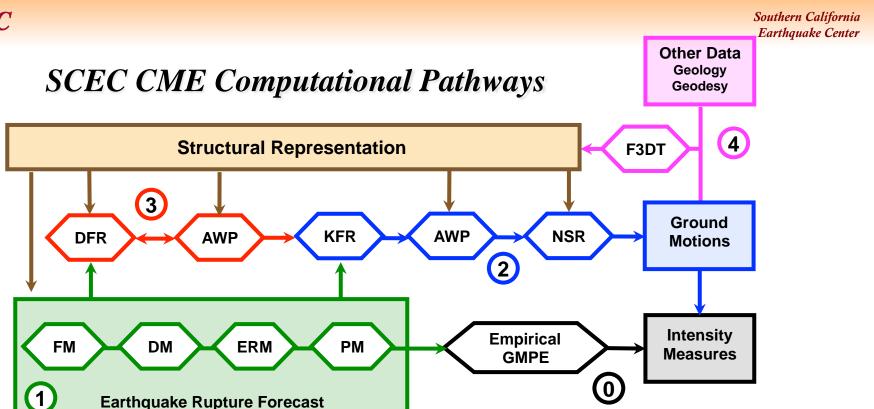
**NSR** = Nonlinear Site Response



#### New HPC Resources Used by SCEC CME Collaboration



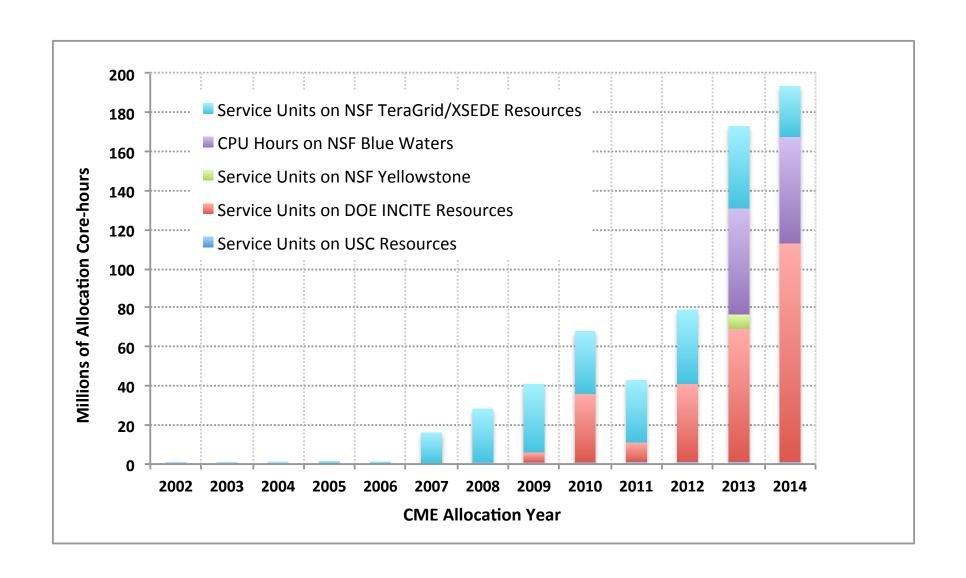




#### **ORNL** Titan **ANL Mira** TACC Stampede NCSA Blue Waters depth = 6 km UCERF3 SA-3s, 2% PoE in 50 years Low High Participation Rates M ≥6.7 Angeles (2) (3) Dynamic rupture model of **Uniform California Earthquake** CyberShake 14.2 seismic Full-3D tomographic model **Rupture Forecast (UCERF3)** fractal roughness on SAF CVM-S4.26 of S. California hazard model for LA region

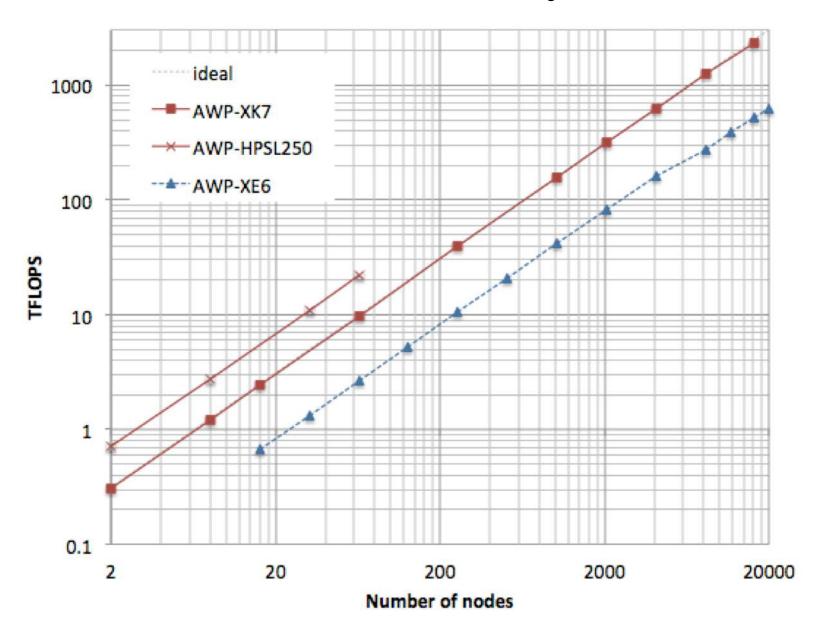


### SCEC use of HPC resources is growing rapidly...





### AWP-ODC Multi-GPU Performance

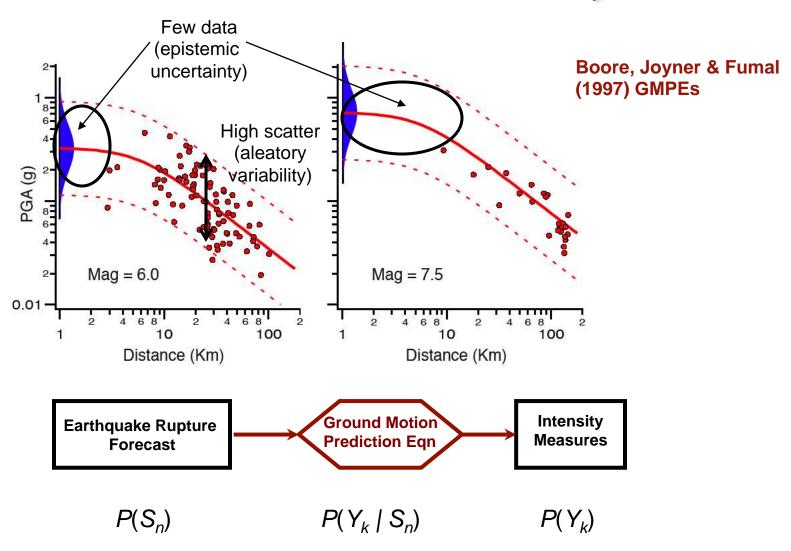




# Formulation of Simulation-Based PSHA



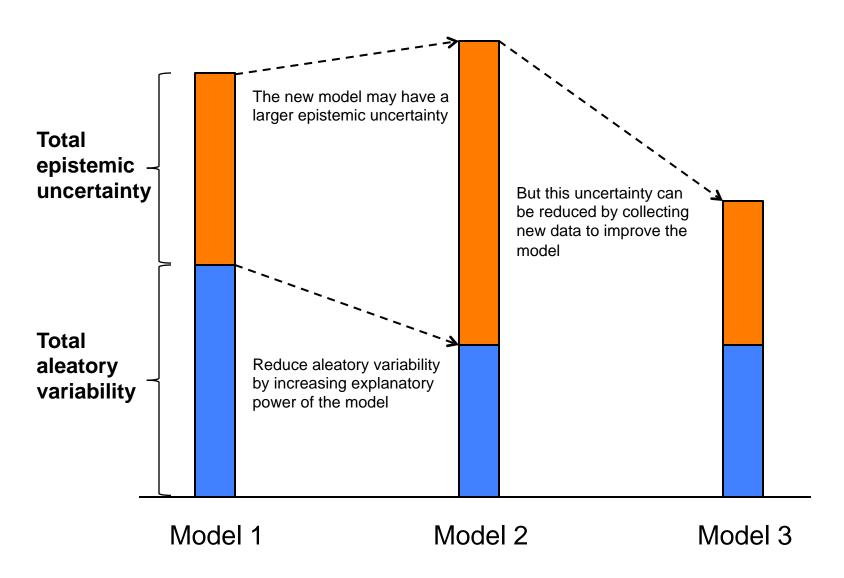
#### Probabilistic Seismic Hazard Analysis



Probabilistic Seismic Hazard Analysis

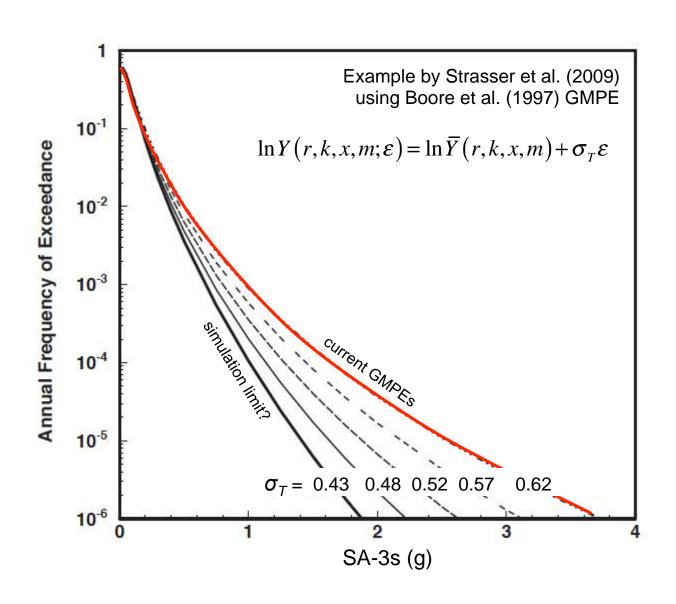


#### Reduction of Aleatory Variability

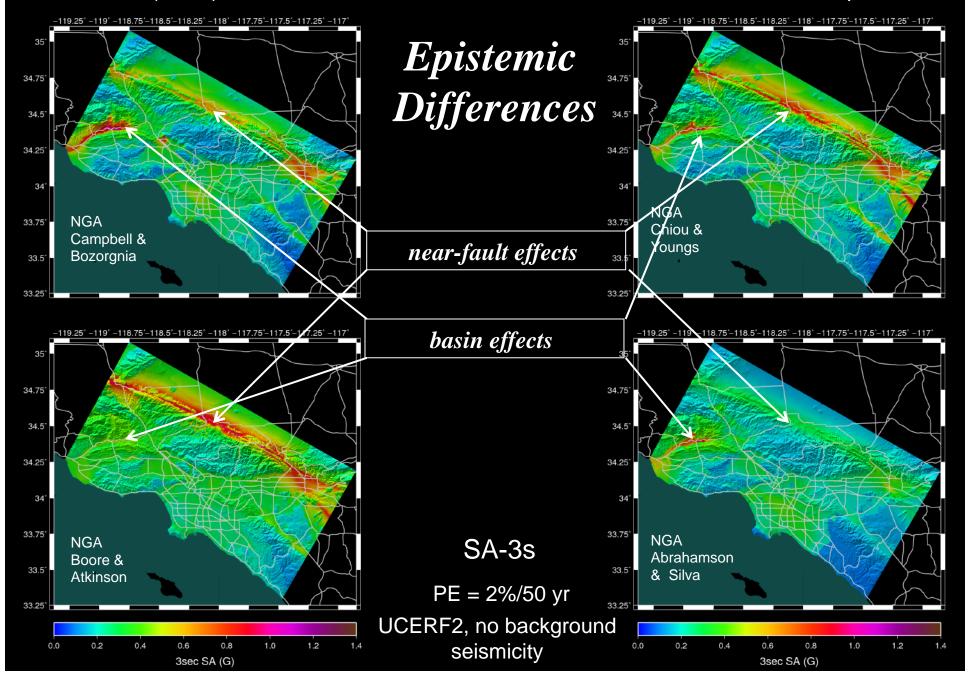




#### Importance of Reducing Aleatory Variability



#### NGA (2008) Attenuation Relations used in National Seismic Hazard Maps





#### Seismological Hierarchy of CyberShake

$$G(r, k, x, s) = \ln Y(r, k, x, s)$$

- Site set:  $r \bowtie R$ 
  - 283 sites in the greater Los Angeles region
  - Elastic structures: BBP-1D, CVM-S4, CVM-H11, or CVM-S4.26
- Rupture set:  $k \times K(r)$ 
  - All UCERF2 ruptures within 200 km of site (~7000 total)
- Conditional hypocenter distribution:  $x \mid \mathbb{X} \mid X(r, k)$ 
  - Uniform distribution along fault strike with  $\Delta x \approx 20 \text{ km}$
- Conditional slip distribution:  $S \boxtimes S(r, k, x)$ 
  - Pseudo-dynamic rupture models of Graves & Pitarka (2007, 2010)
  - Approximately 415,000 rupture variations per site, 235 million synthetic seismograms per model (2 horizontal components)

CHD and CSD define the "Extended ERF"



#### Ground Motion Prediction Equations

#### Formulation of time-independent PSHA for empirical GMPEs:

$$P(Y>y;r,T) = 1 - e^{-\lambda(Y>y|r)T} \text{ conditional hypocenter distribution (CHD)} \text{ conditional magnitude distribution (CMD)}$$

$$\lambda(Y>y|r) = \sum_{k \in K} v_k \sum_{x \in X(k)} p(x|k) \sum_{s \in S(k,x)} p(m|k) P(Y>y|r,k,x,m)$$

$$P(Y>y|r,k,x,m) = \int_{-\infty}^{+\infty} f(\varepsilon) H[\ln Y(r,k,x,m;\varepsilon) - \ln y] d\varepsilon$$

$$\ln \overline{Y}(r,k,x,m) = F_1(r) + F_2(r,k) + F_3(r,k,x) + F_4(k,m)$$

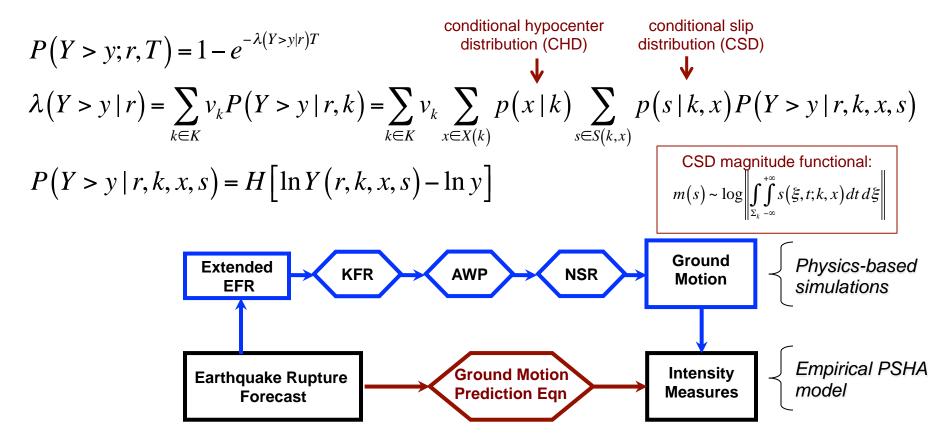
$$\begin{cases} F_1 & \text{ site effect path effect path effect path effect for the path effect of the path effect for the path$$





#### CyberShake Hazard Model

#### Formulation of time-independent PSHA for CyberShake simulations:



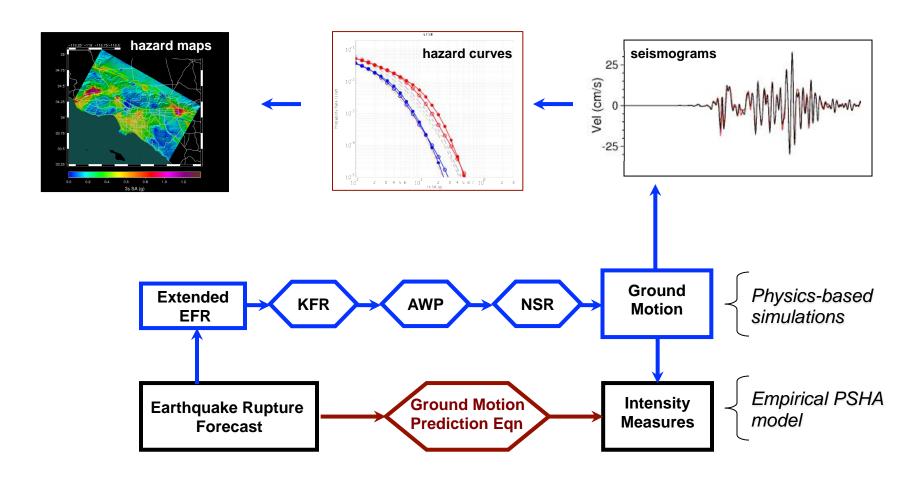
KFR = kinematic fault rupture model

AWP = anelastic wave propagation model

**NSR** = nonlinear site response



### CyberShake Hazard Model



KFR = kinematic fault rupture model

**AWP** = anelastic wave propagation model

**NSR** = nonlinear site response



#### CyberShake CS11 Hazard Model

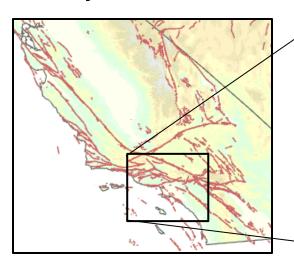
R. Graves, T. H. Jordan, S. Callaghan, E. Deelman, E. Field, G. Juve, C. Kesselman, P. Maechling, G. Mehta, K. Milner, D. Okaya, P. Small, and K. Vahi (2011)

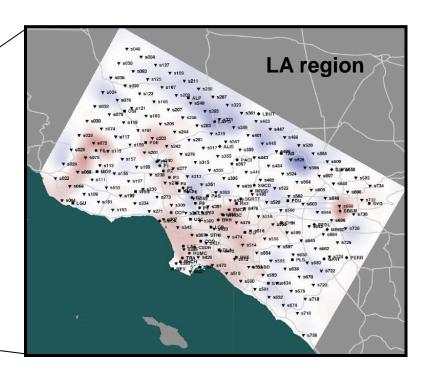
#### 225 sites in LA region (f < 0.5 Hz)

- 410,000 rupture variations per site
- total of 185 million seismograms (N & E components)

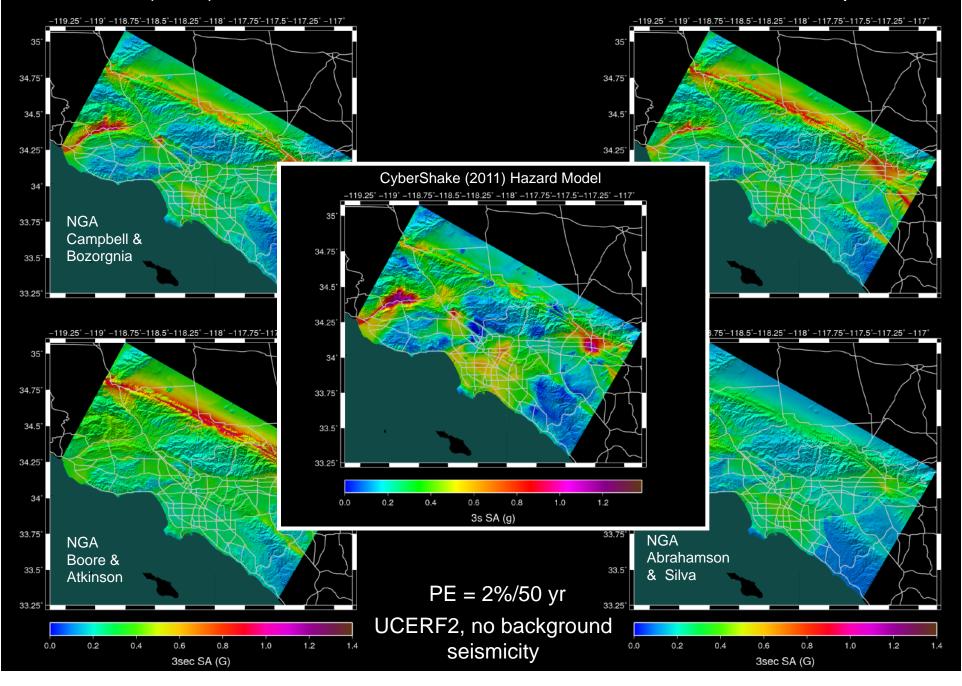
#### Run on TACC Ranger (5.3 million hrs, 4,400 cores, 50 days)

- 189 million jobs
- 46 petabytes of total I/O
- 176 terabytes of total output data
- 2.1 terabytes of archived data





#### NGA (2008) Attenuation Relations used in National Seismic Hazard Maps





## Introduction to the CyberShake Computational Platform



# CyberShake Platform: Physics-Based PSHA Essential ingredients

#### 1. Extended earthquake rupture forecast

- probabilities of all fault ruptures (e.g., UCERF2)
- conditional hypocenter distributions for rupture sets
- conditional slip distributions from pseudo-dynamic models

#### 2. Three-dimensional models of geologic structure

- large-scale crustal heterogeneity
- sedimentary basin structure
- near-surface properties ("geotechnical layer")

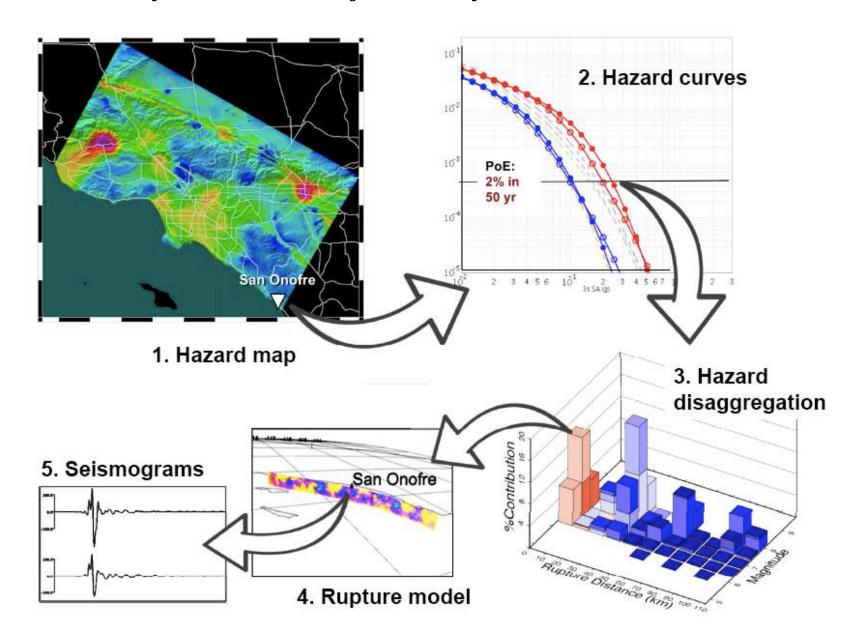
#### from SCEC CVMs

#### 3. Ability to compute large suites (> 108) of seismograms

- efficient anelastic wave propagation (AWP) codes
- reciprocity-based calculation of ground motions



#### CyberShake Platform: Physics-Based PSHA





#### Computational Efficiency of Seismic Reciprocity

- To account for source variability requires very large sets of simulations
  - 7,000 ruptures from UCERF2; 415,000 rupture variations
- Ground motions can be calculated at much smaller number of surface sites to produce hazard map
  - 283 in LA region, interpolated using empirical attenuation relations
- Elastodynamic representation theorem

$$u_n(x,t) = \int_{-\infty}^{\infty} d\tau \int_{\Sigma} d\sigma(\xi) \frac{\partial}{\partial \xi_j} G_{ni}(x,t;\xi,\tau) \ \Gamma_{ij}(\xi,t-\tau)$$

Reciprocity

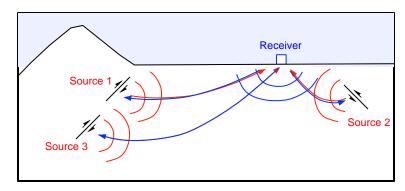
$$G_{ni}(x,t;\xi,\tau) = G_{ni}(\xi,-\tau;x,-t)$$

Strain Green tensor (SGT)

$$H_{ijn}(x,t;\xi,\tau) = \frac{1}{2} \left[ \frac{\partial}{\partial x_i} G_{jn}(x,t;\xi,\tau) + \frac{\partial}{\partial x_j} G_{in}(x,t;\xi,\tau) \right]$$

Site-oriented simulation

$$u_n(x,t) = \int_{-\infty}^{\infty} d\tau \int_{\Sigma} d\sigma(\xi) H_{ijn}(\xi,\tau;x,t) \Gamma_{ij}(\xi,t-\tau)$$



M sources to N receivers requires M simulations

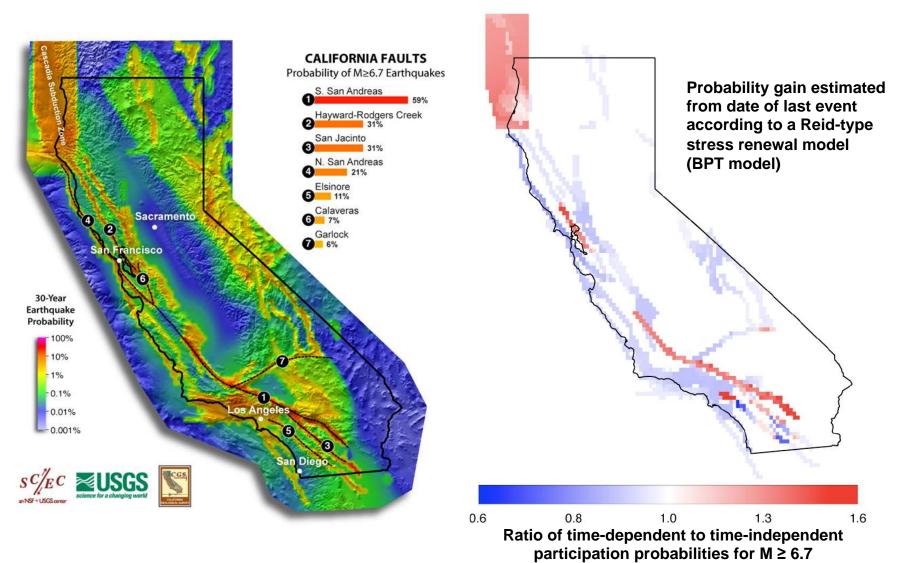
M sources to N receivers requires 2N or 3N simulations

Use of reciprocity reduces CPU time by a factor of ~1,000



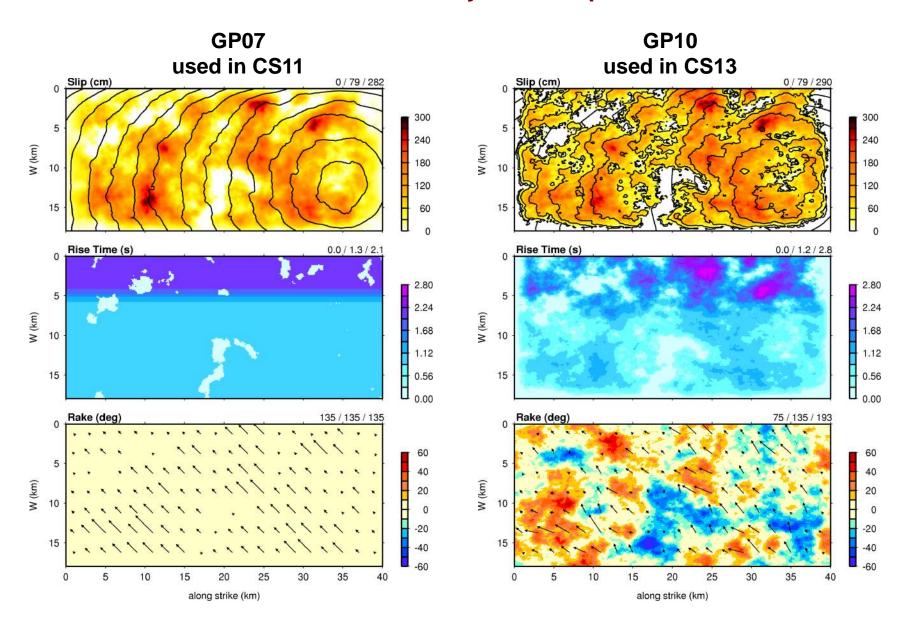
### Working Group on California Earthquake Probabilities (2007)

### Uniform California Earthquake Rupture Forecast (UCERF2)



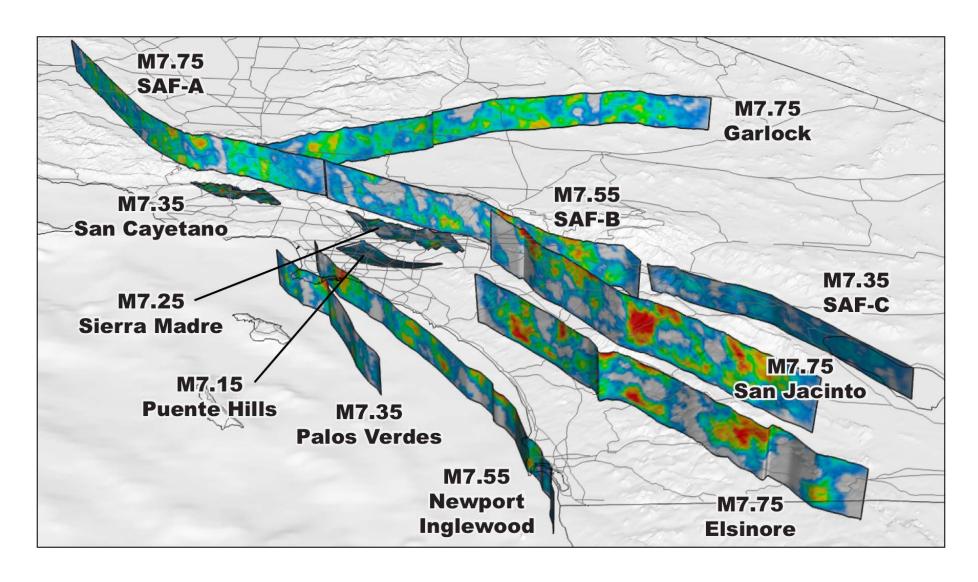


# Conditional Slip Distribution Graves-Pitarka Pseudo-Dynamic Rupture Models

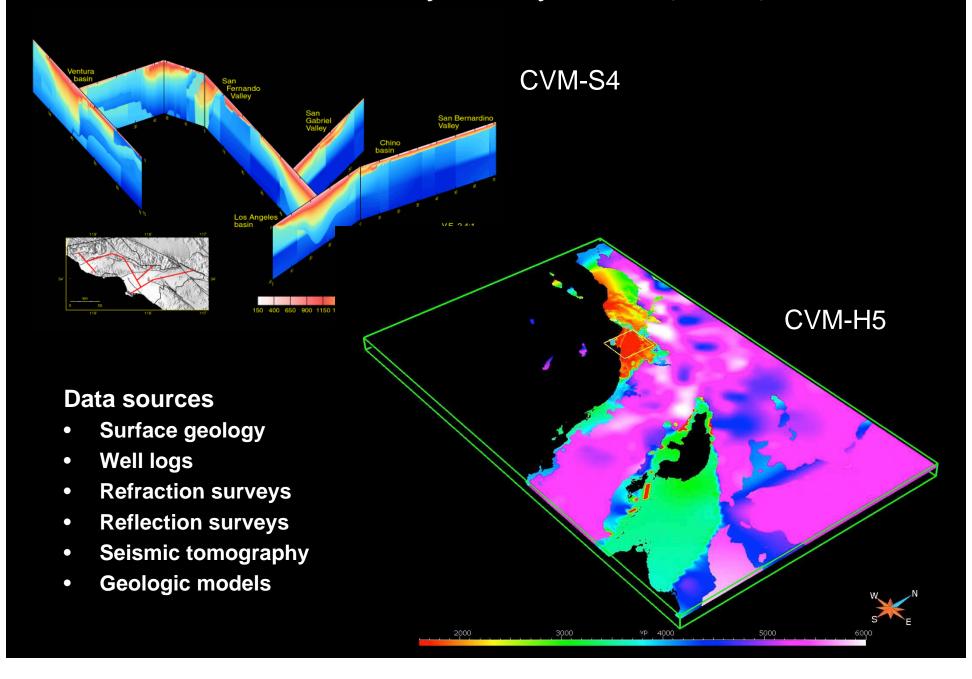




### CyberShake Rupture Models

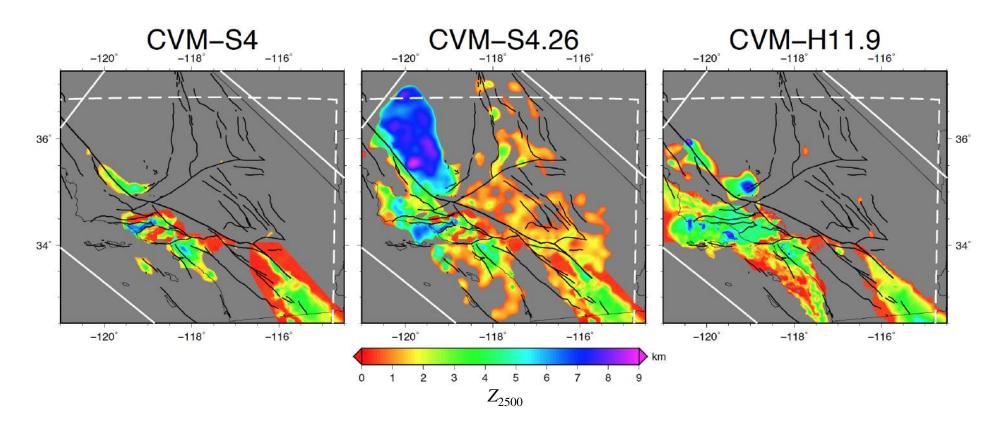


### SCEC Community Velocity Models (CVMs)





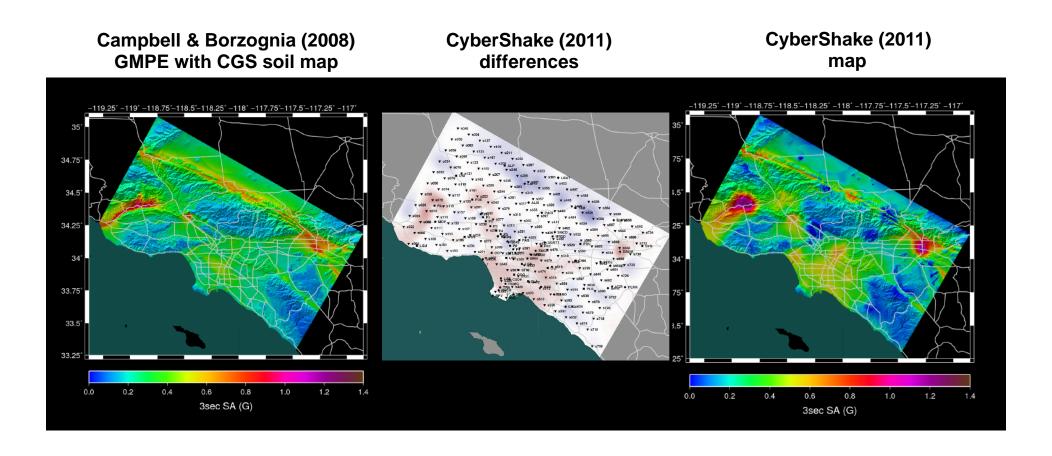
### Basin Structures



 $Z_{2500}$ : iso-velocity surfaces at  $V_{\rm S} = 2.5$  km/s



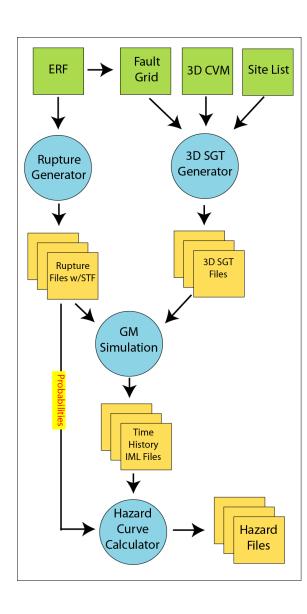
### CyberShake Hazard Map Interpolation



3-s Spectral Acceleration (in g) at Probability of Exceedance = 2% in 50 yr



### CyberShake Workflow



### **ERF (Earthquake Rupture Forecast)**

Defines fault surfaces, dimensions, segmentation, magnitudes and rupture probabilities

#### **Rupture Generator**

Generates full kinematic rupture description given fault geometry / dimension and magnitude. Includes slip distribution, hypocenter location, rupture propagation and slip time function (STF).

#### SGT (Strain Green's Tensor) Generator

3D finite difference simulation code to calculate SGTs at each site of interest. SGTs are computed using reciprocity by inserting a force at the site location and recording the strains on all potential fault surfaces. Storage of SGT files is on the order of 250 GBytes per site.

### **GM (Ground Motion) Simulation**

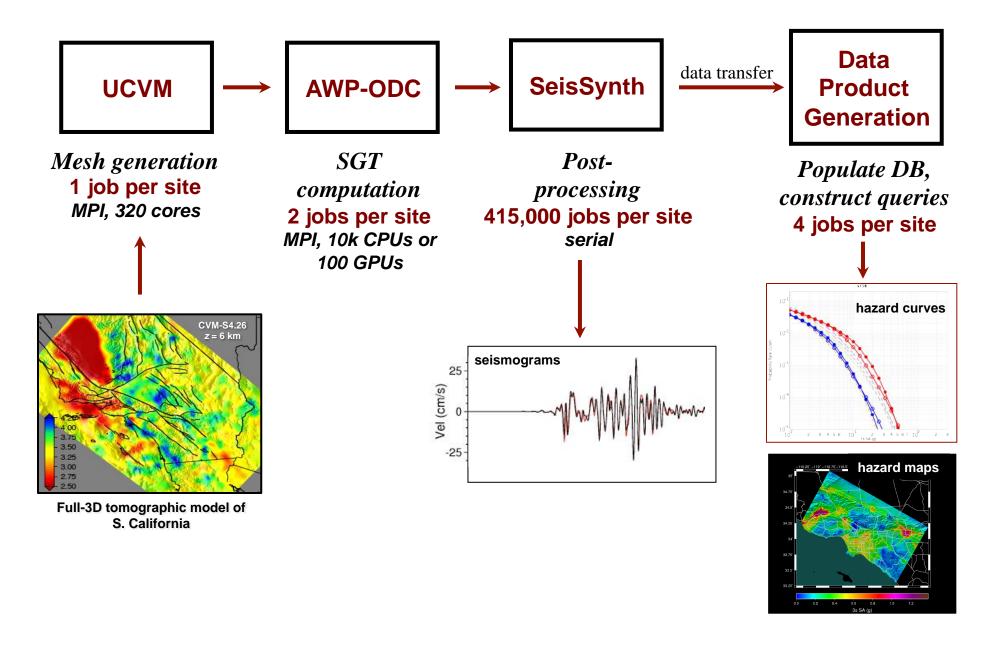
Each rupture is simulated by convolving the SGTs appropriate for the specific fault with the kinematic rupture parameters. The output of the simulation is a time history of the ground motion at the site for the given rupture. Spectral acceleration (SA) values are also computed and stored for each time history.

#### **Hazard Curve Calculator**

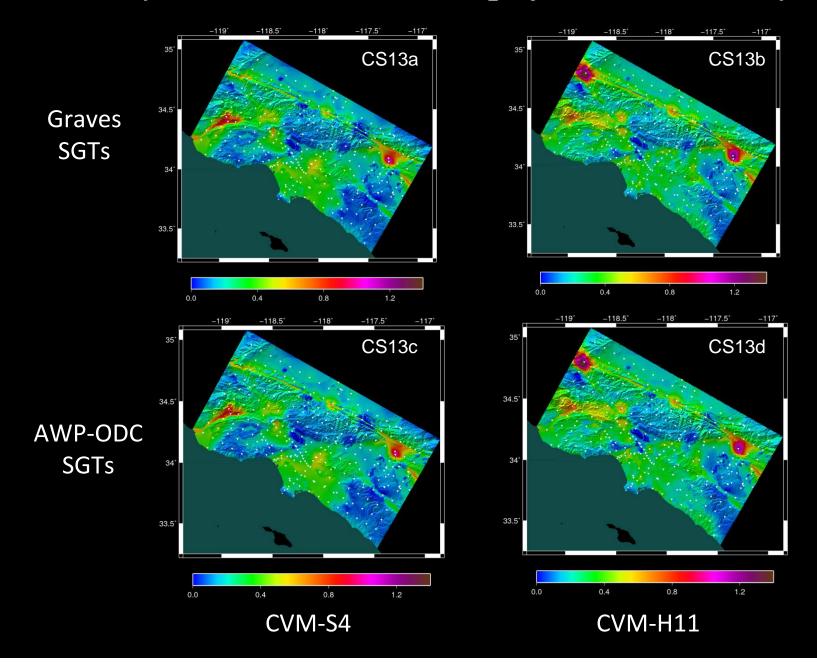
Hazard curves are defined as the probability of exceeding a particular ground motion level (IML) in a specified time span. The curves are computed by combining the occurence probability and simulated ground motion for each rupture, and then integrating over all possible ruptures.

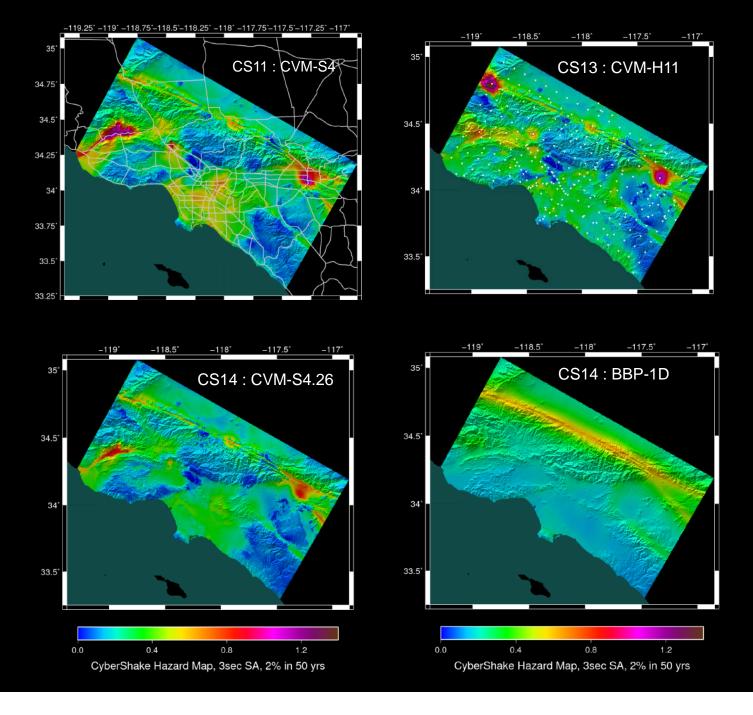


## CyberShake Workflow



## CyberShake Hazard Maps from CS13 Study







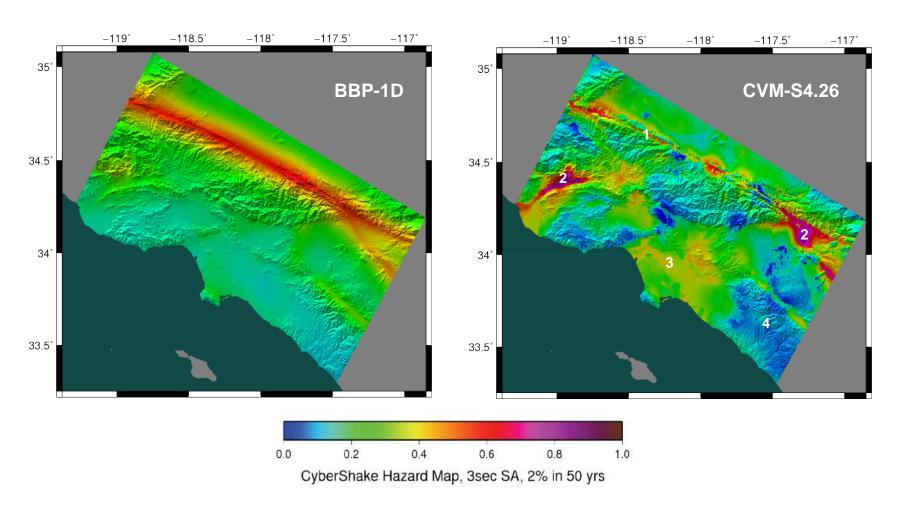
### CyberShake Workflow

### Computational statistics for CS14.2 study:

- Reservation for 700 XE nodes, 200 XK nodes
- 1144 CyberShake sites
  - 568 with SGT CPU
    - 2792 sec/job x 313.8 nodes = 243.4 node-hrs
    - Queue time: mean 973 sec, median 191 sec
  - 568 with SGT GPU
    - 1338 sec/job x 100 nodes = 37.2 node-hrs (6.5x efficiency improvement)
    - Queue time: mean 2889 sec, media 731 sec
- 99.8 million tasks produced 470 million seismograms
  - 81 tasks/sec
- 31,463 jobs submitted remotely to the Blue Waters queue
- 860 TB of data managed
  - 57 TB output files
  - 12 TB staged back to SCEC storage



# Comparison of 1D and 3D CyberShake Models for the Los Angeles Region





## CyberShake Workflow

### **Los Angeles Region Hazard Models (1144 sites)**

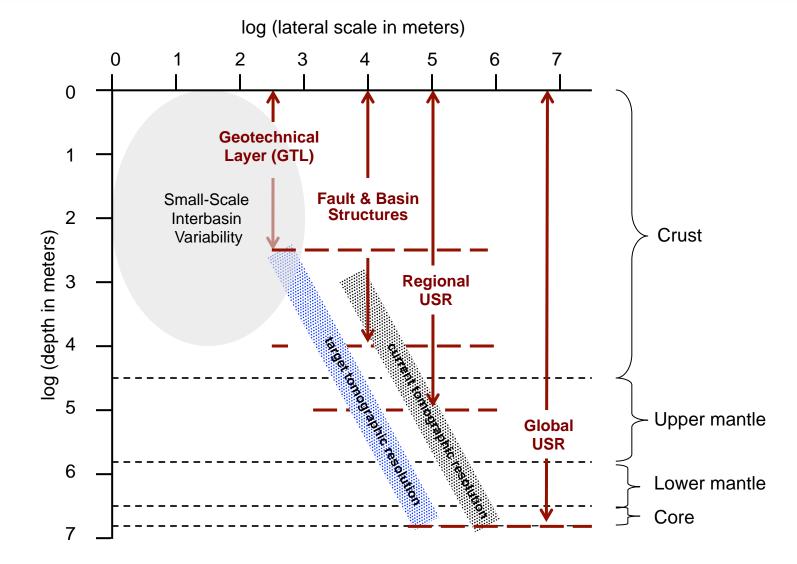
CyberShake Application Metrics (Hours)	2008 (Mercury, normalized)	2009 (Ranger, normalized)	2013 (Blue Waters / Stampede)	2014 (Blue Waters)
Application Core Hours:	19,488,000 (CPU)	16,130,400 (CPU)	12,200,000 (CPU)	15,800,000 (CPU +GPU)
Application Makespan:	70,165	6,191	1,467	342

Metric	2013 (Study 13.4)	2014 (Study 14.2)
Simultaneous processors	21,100 (CPU)	46,720 (CPU) + 160 (GPU)
Concurrent Workflows	5.8	26.2
Job Failure Rate	2.6%	1.3%
Data transferred	52 TB	12 TB



# 3D Seismic Velocity Structure from Full-3D Inversion







# CVM-S4.26 Structure for Southern California

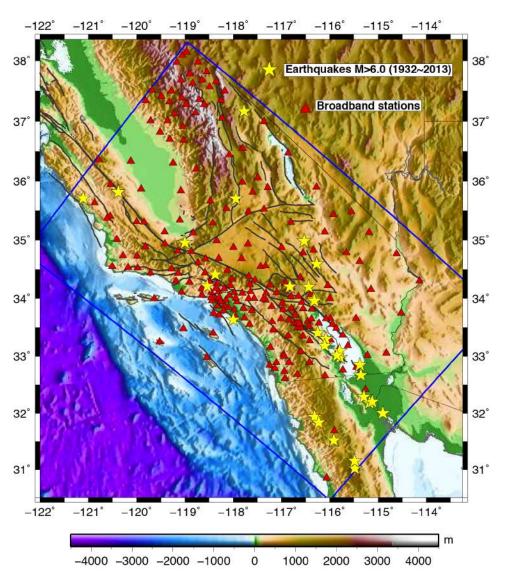
<sup>1</sup>En-Jui Lee, <sup>2</sup>Po Chen, <sup>1</sup>Thomas H. Jordan, <sup>1</sup>Philip Maechling, <sup>3</sup>Marine Denolle, <sup>3</sup>Greg Beroza

> <sup>1</sup>University of Southern California, <sup>2</sup>University of Wyoming, <sup>3</sup>Stanford University



### CVM-S4.26

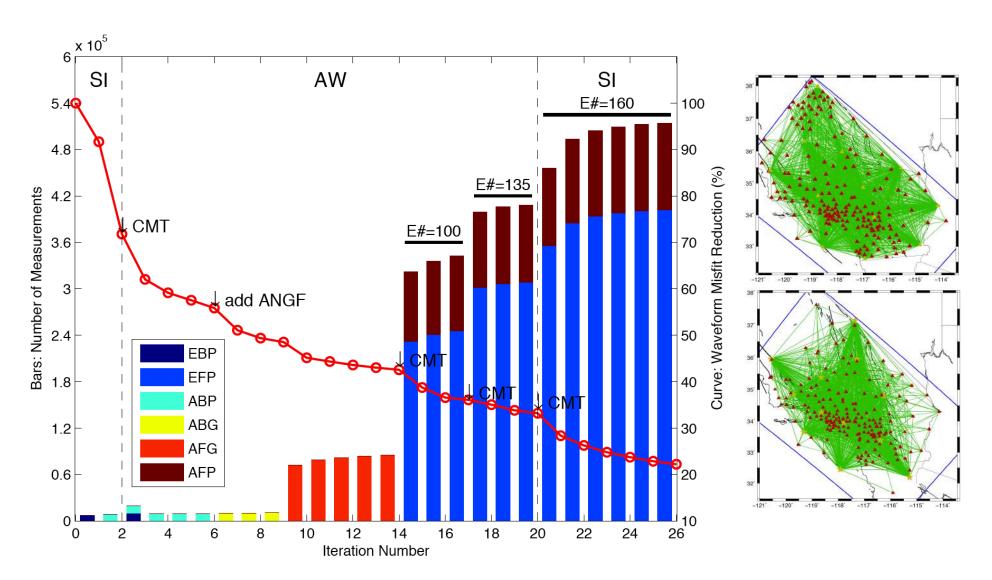
### Full-3D tomography model of Southern California crustal structure



- CVM-S4 starting model
- 26<sup>th</sup> iterate of a full-3D tomographic (F3DT) inversion procedure (Lee et al., 2013).
- Data sets comprise ~ 550,000 differential waveform measurements at f ≤ 0.2 Hz
  - 38,000 earthquake seismograms
  - 12,000 ambient-noise Green functions
- Nonlinear iterative process involved two methods:
  - adjoint-wavefield (AW-F3DT)
  - scattering-integral (SI-F3DT)

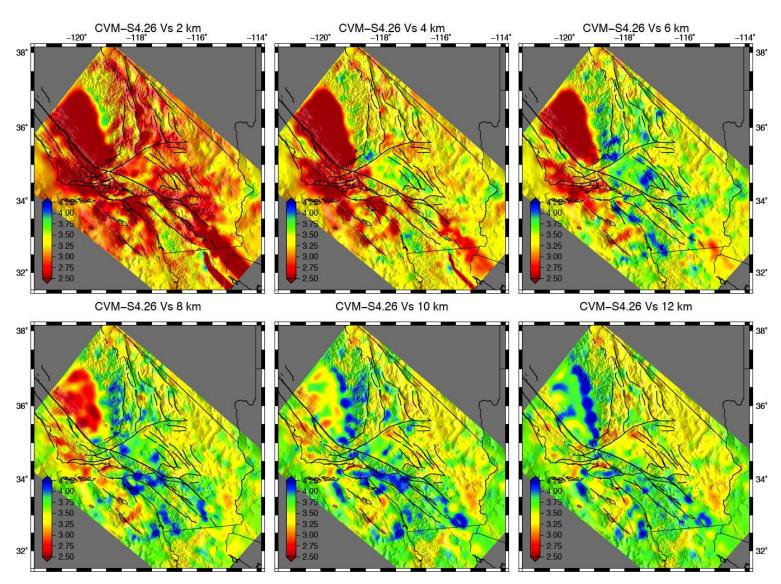


CVM-S4.26 Full-3D tomography model of Southern California crustal structure



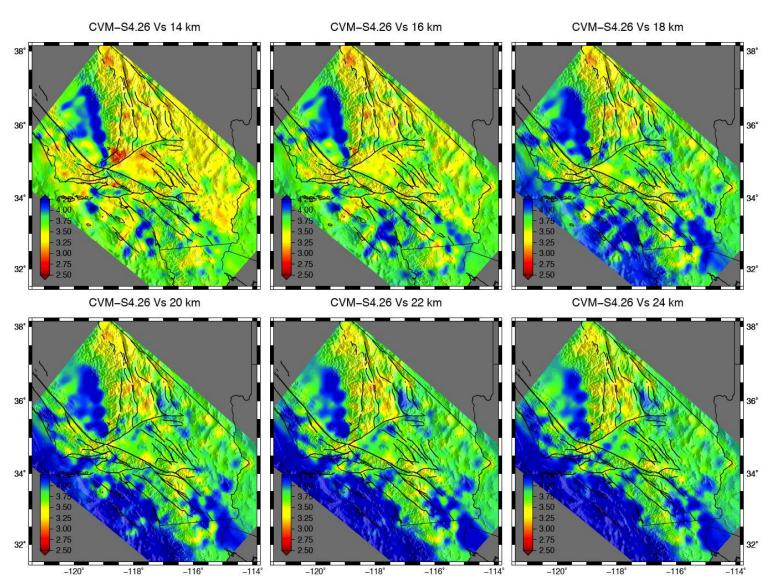


CVM-S4.26 Full-3D tomography model of Southern California crustal structure



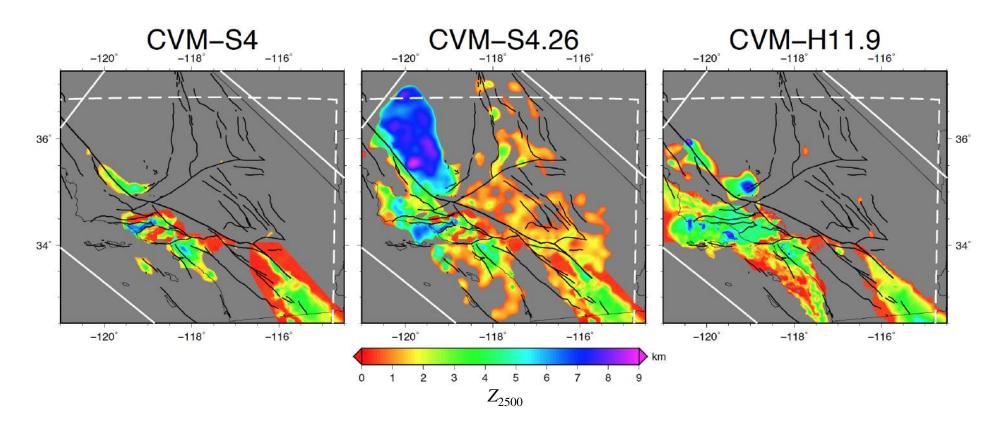


CVM-S4.26 Full-3D tomography model of Southern California crustal structure





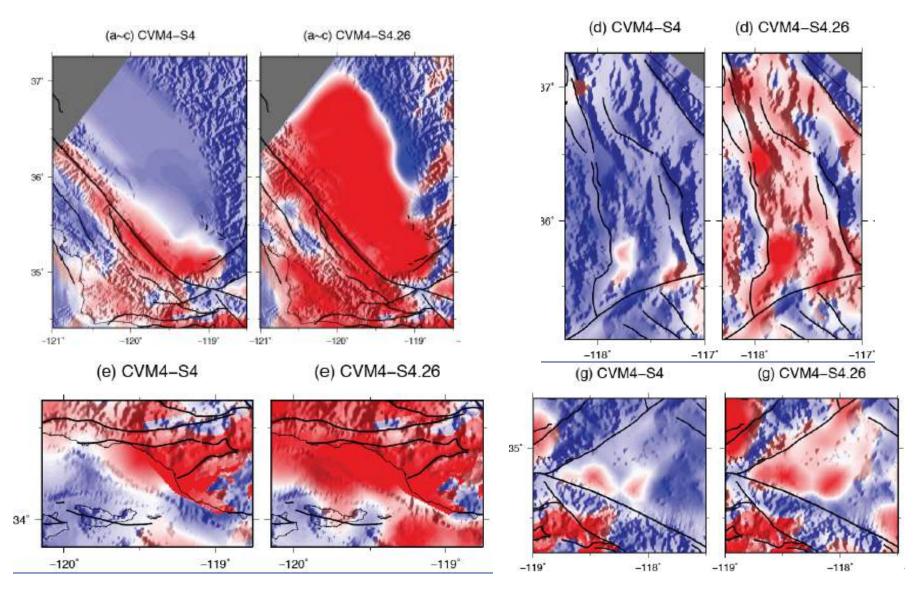
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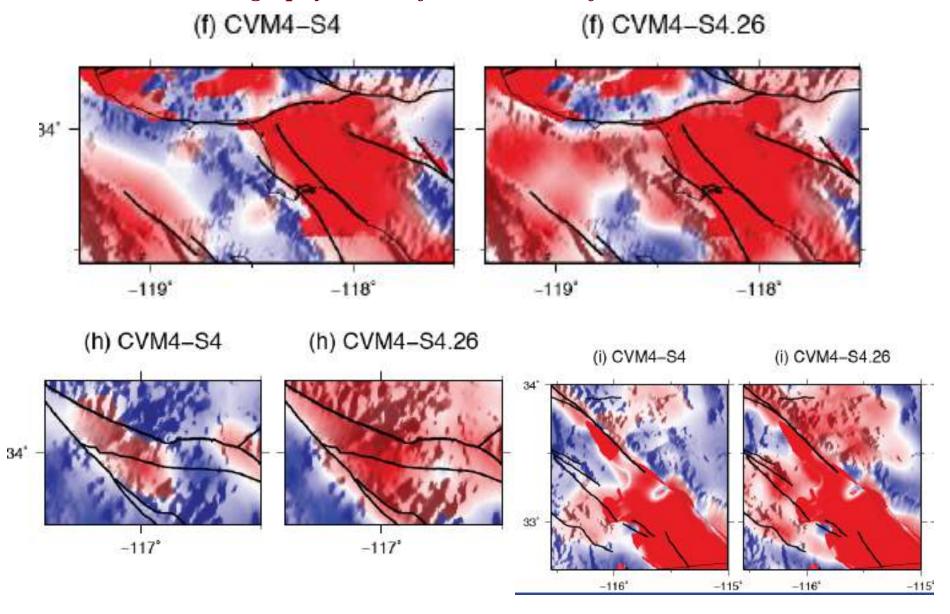
CVM-S4.26 Full-3D tomography model of Southern California crustal structure





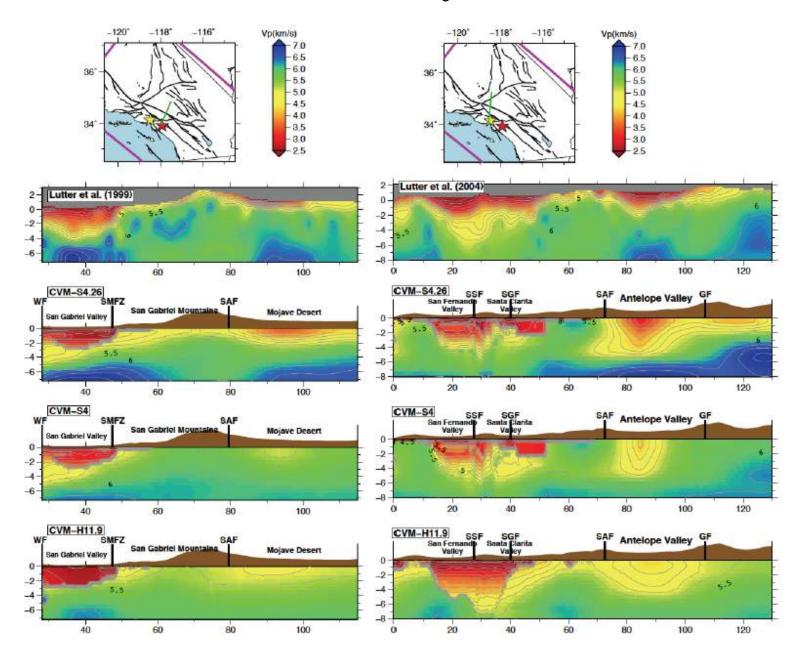
CVM-S4.26

Full-3D tomography model of Southern California crustal structure

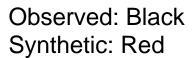


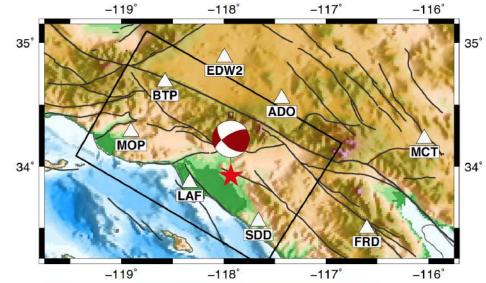


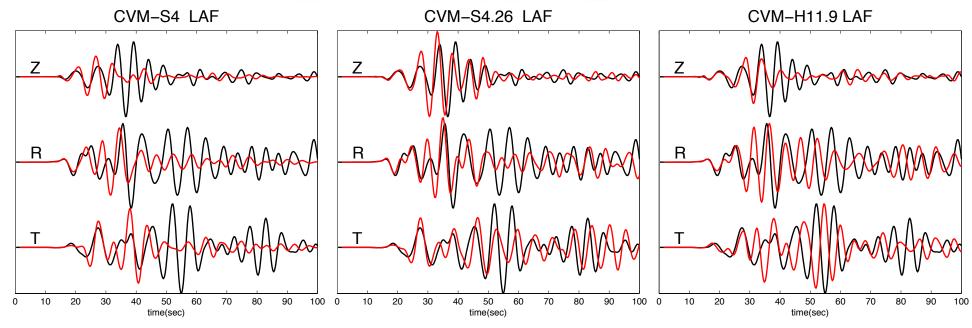
### LARSE Profiles



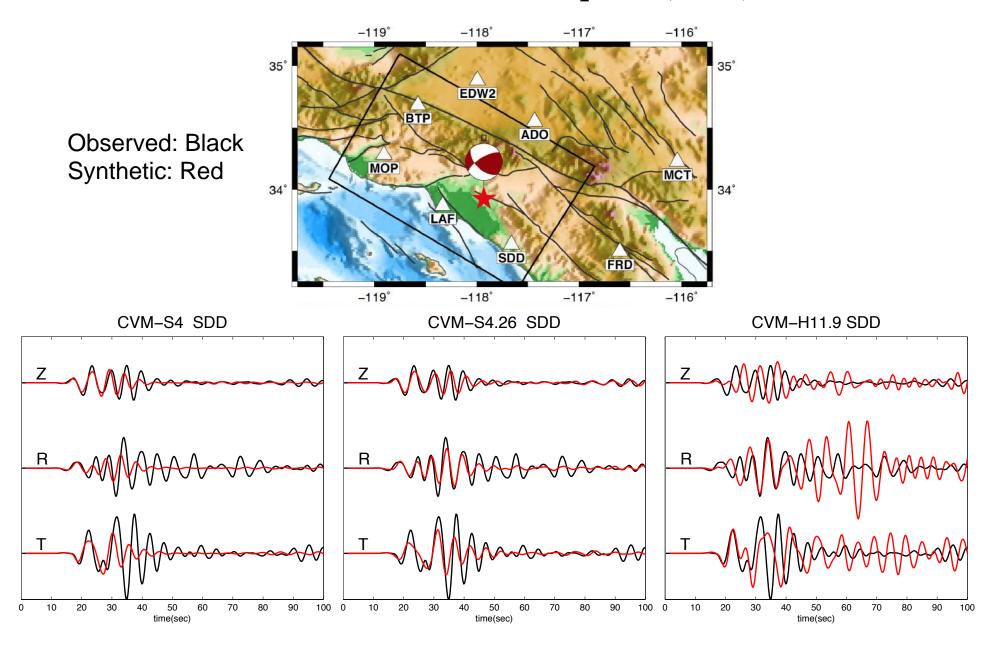




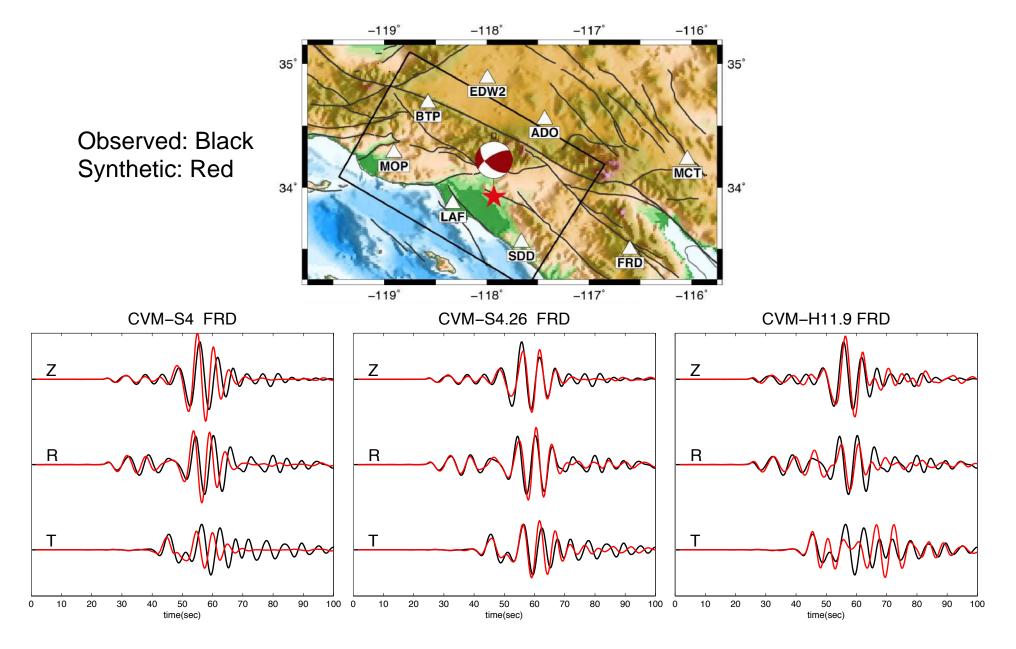












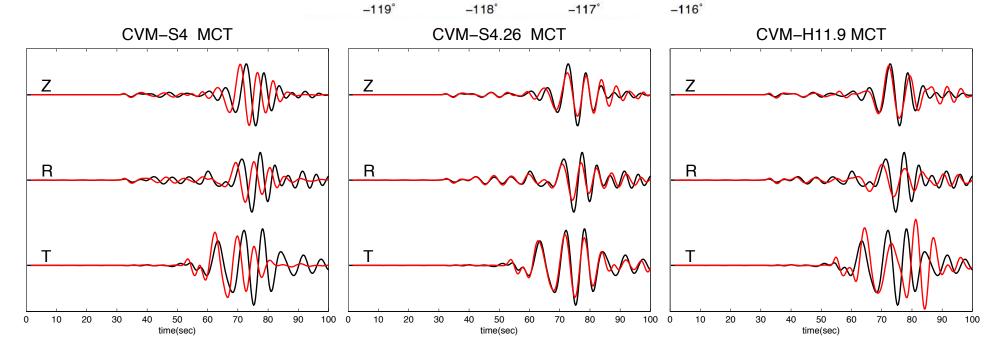


-117°

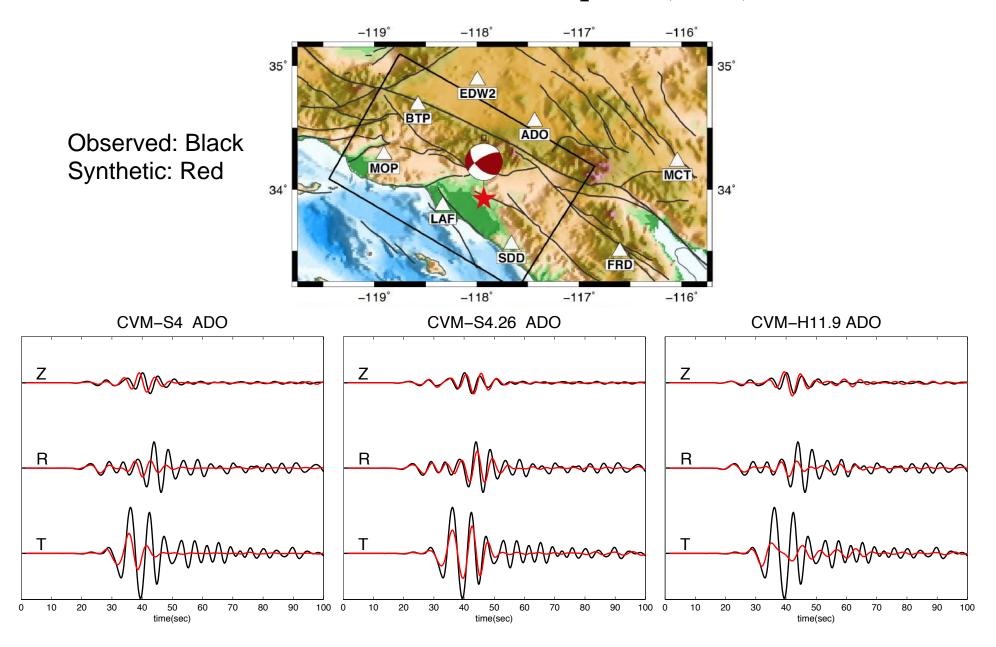
-116°

-118°









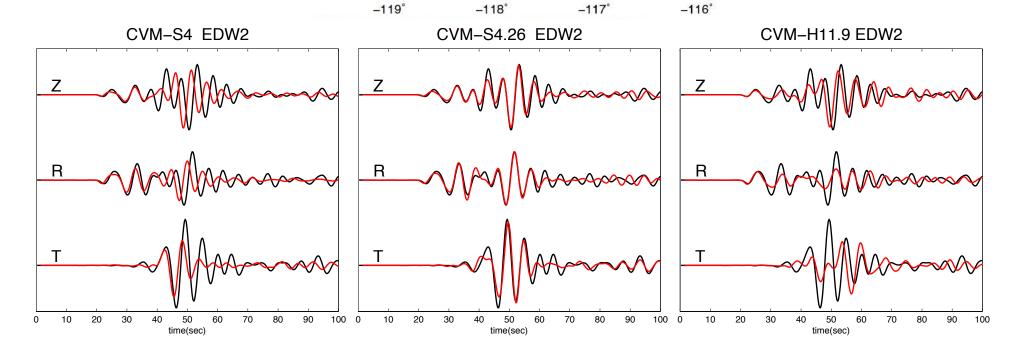


-117°

-116°

-118°



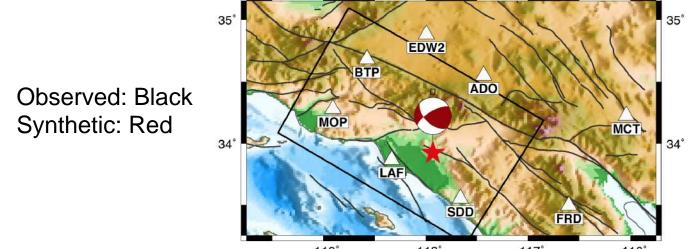


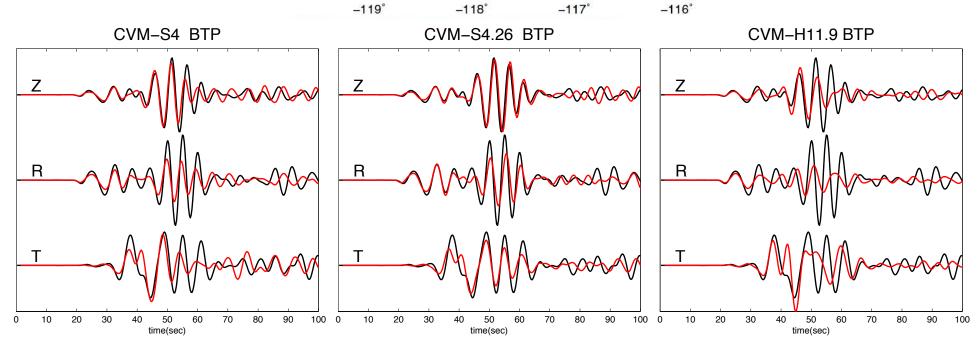


-117°

-116°

-118°



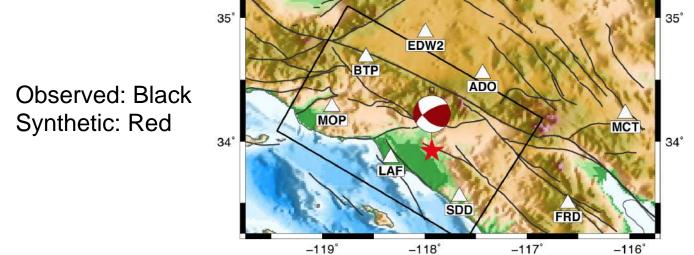


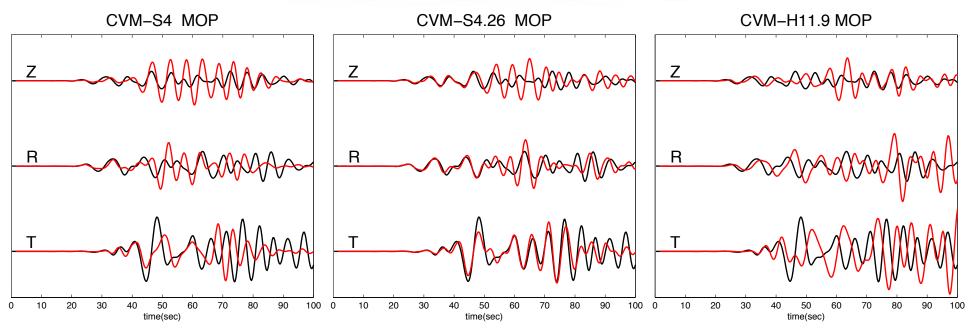


-117°

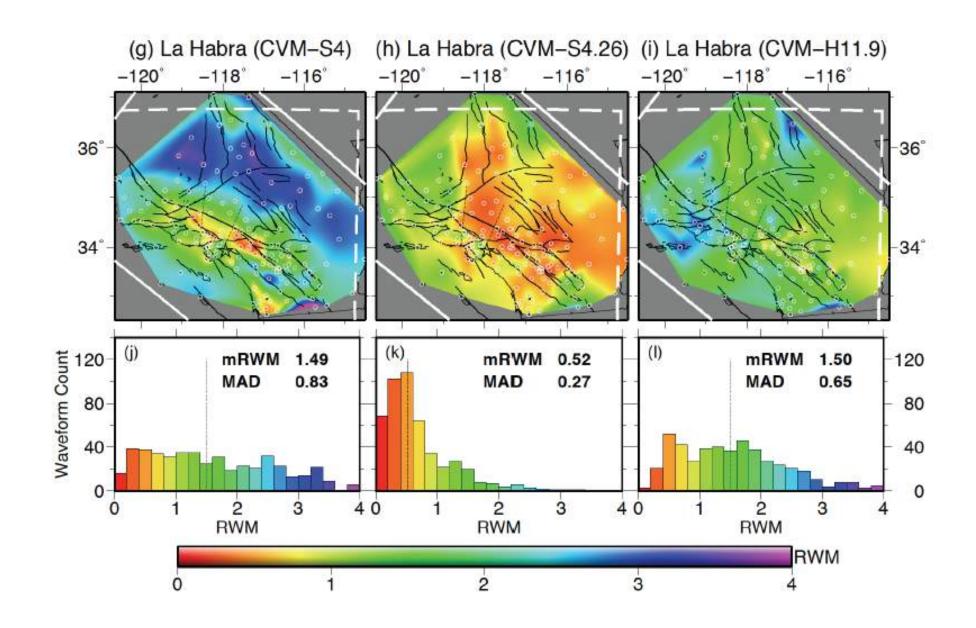
-116°

-118°



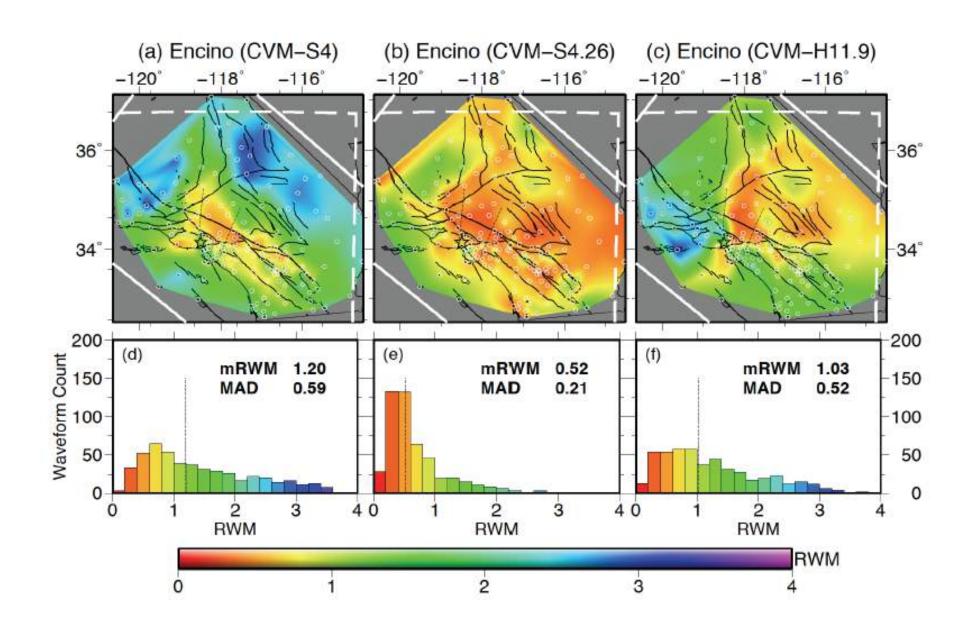








### 03/17/14 Encino Earthquake (M4.4)



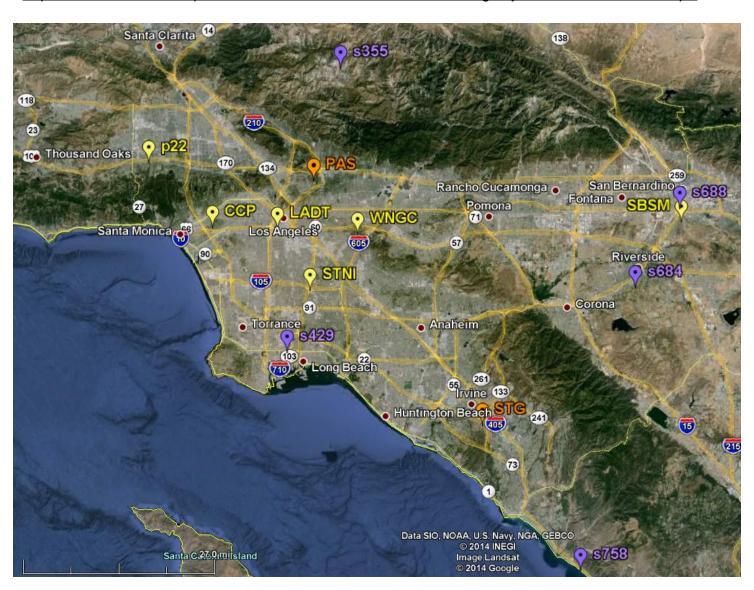


# Comparisons Among CyberShake Models and NGA GMPEs

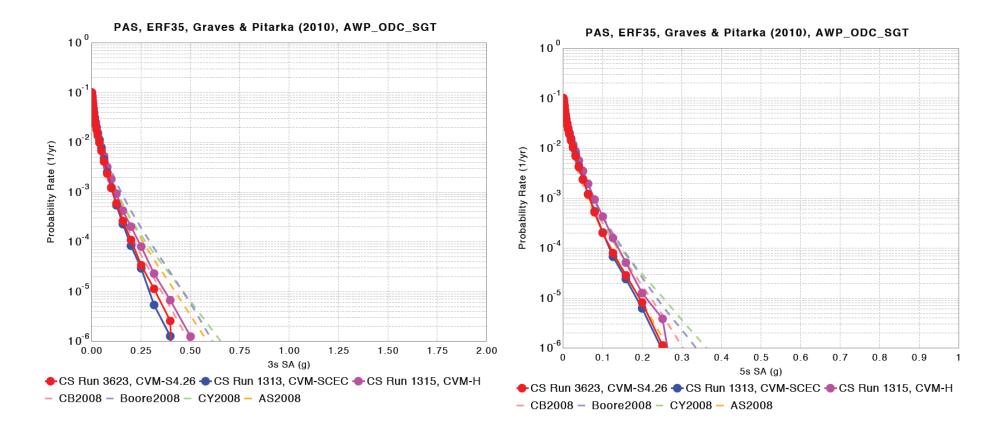


### Sites for NGA-CyberShake Comparisons

http://scec.usc.edu/scecpedia/SCEC UGMS Committee Meeting#CyberShake Hazard Maps

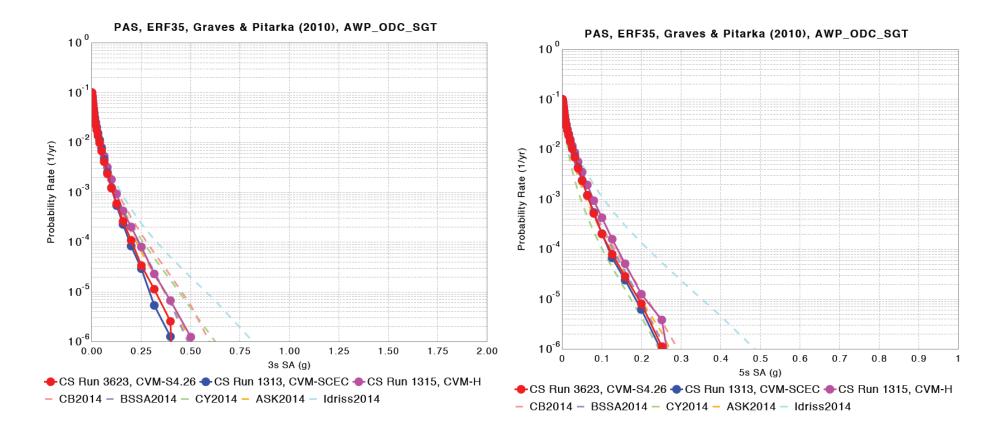






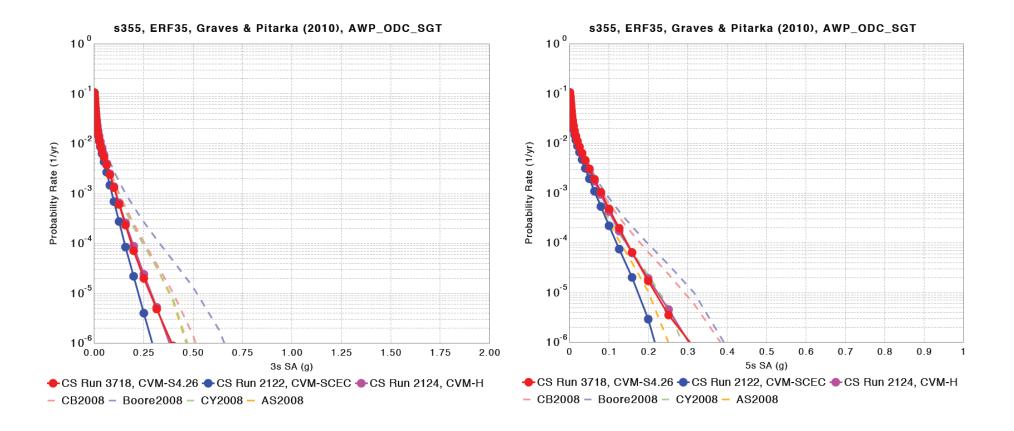
**Site PAS** 





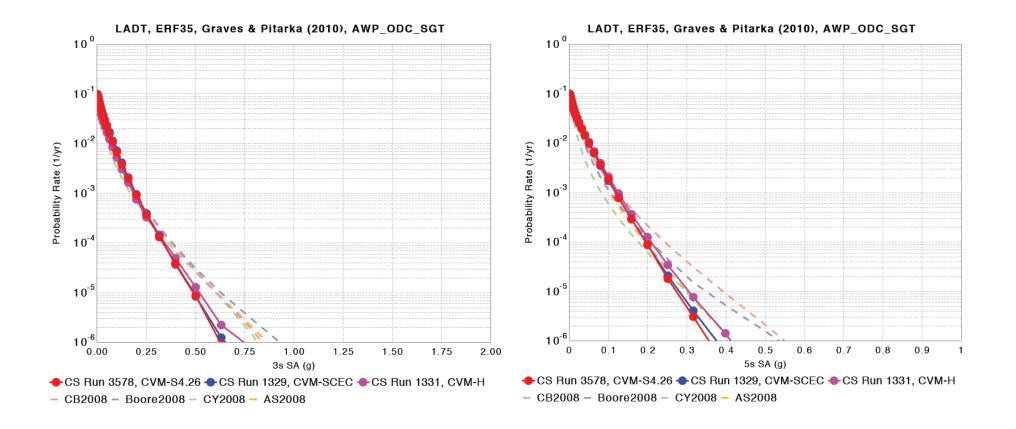
**Site PAS** 





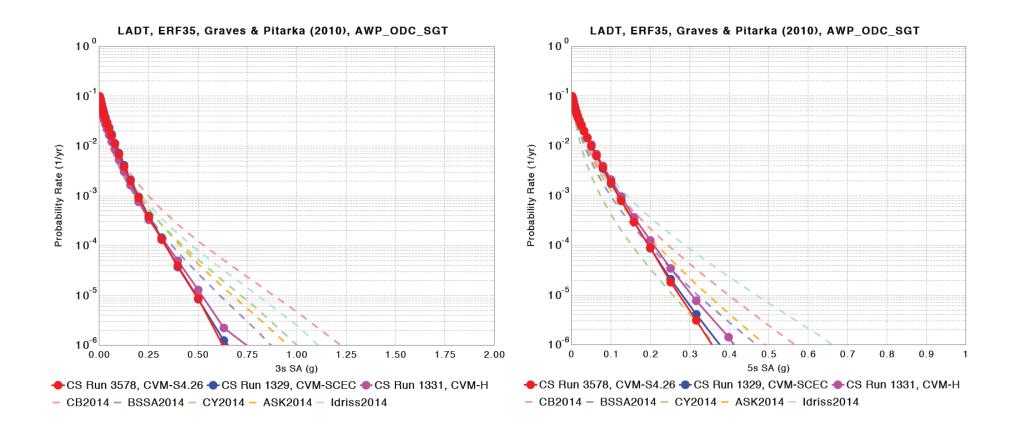
**Site s355** 





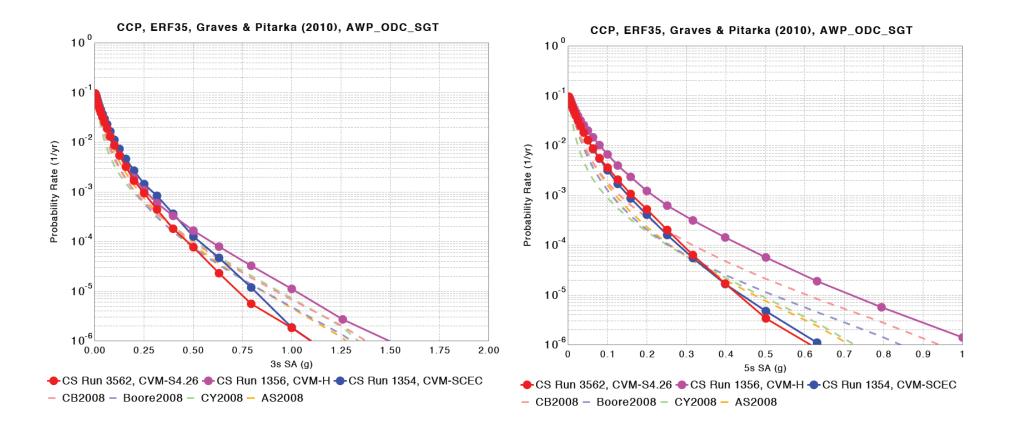
**Site LADT** 





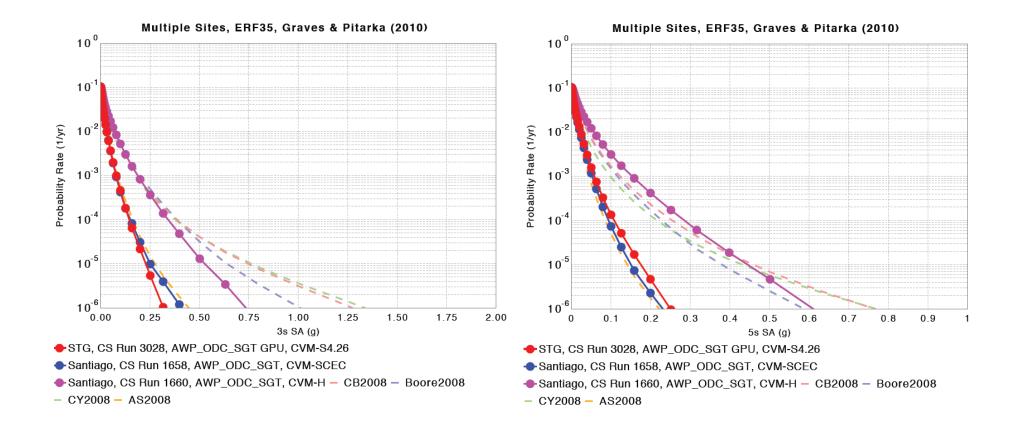
**Site LADT** 





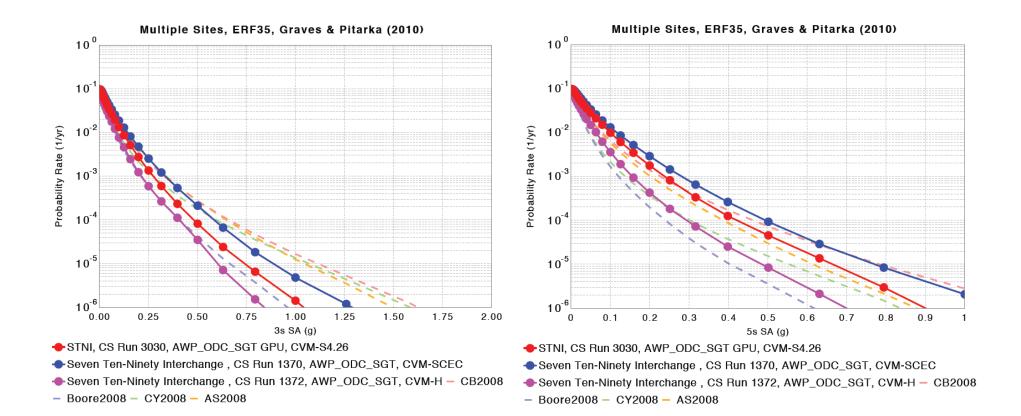
#### **Site CCP**





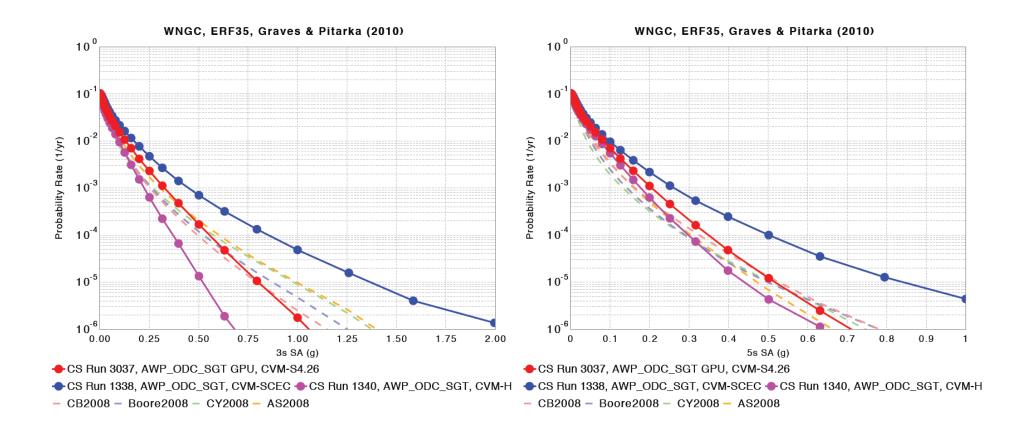
Site SGT





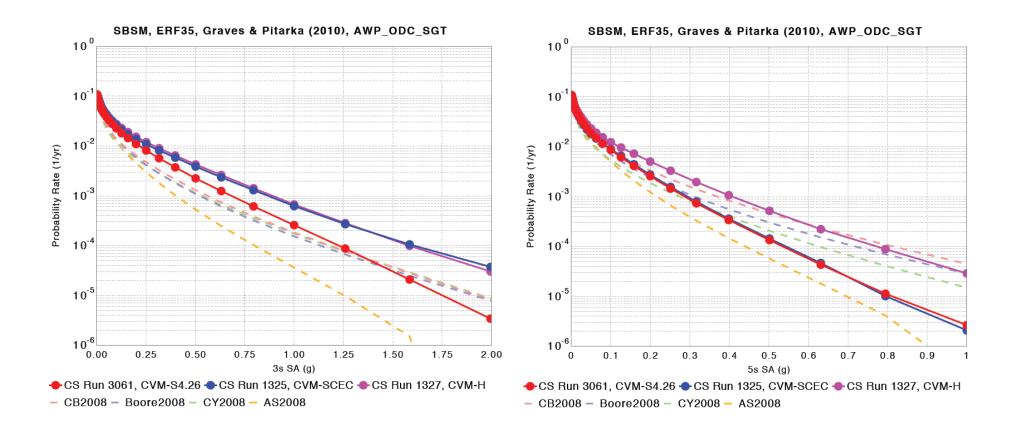
#### Site STNI





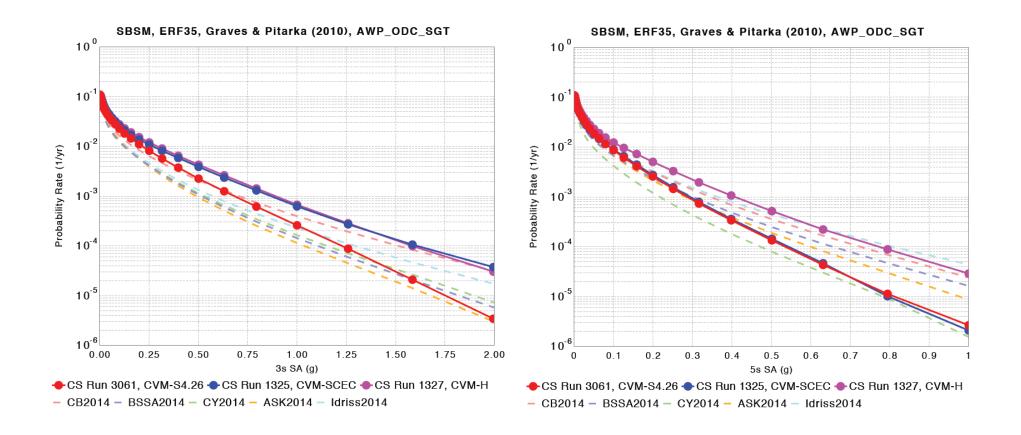
#### **Site WNGC**





**Site SBSM** 





Site SBSM

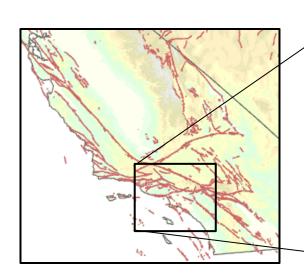


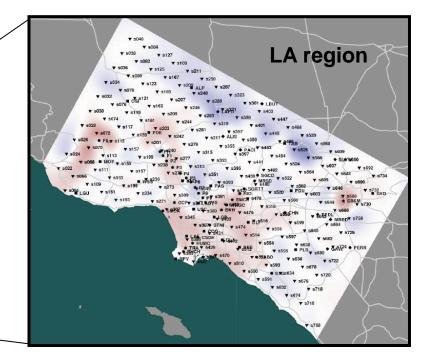
### Seismological Hierarchy of CyberShake

 $G(r, k, x, s) = \ln Y(r, k, x, s)$ 

- Site set:  $r \bowtie R$ 
  - 283 sites in the greater Los Angeles region
  - Regional structure specified by CVM-S4 or CVM-H11
- Rupture set:  $k \bowtie K(r)$ 
  - All UCERF2 ruptures within 200 km of site
- Conditional hypocenter distribution:  $x \times X(r, k)$ 
  - Uniform distribution along fault strike with  $\Delta x \approx 20$  km
- Conditional slip distribution:  $s \bowtie S(r, k, x)$ 
  - Pseudo-dynamic rupture models of Graves & Pitarka (2007, 2010)

Approximately 415,000 rupture variations per site, 235 million synthetic seismograms per model







#### Averaging-Based Factorization

- GMPEs are the multiplication of factors representing attenuation, site effects, directivity effects, etc.
  - This model-based factorization is not available for CyberShake
- We can compare simulation-derived models with GMPEs using "averaging-based factorization" (Wang & Jordan, BSSA, 2014)
  - Expected shaking intensities are constructed from a hierarchy of averaging operations over slip variations (s), hypocenters (x), sources (k), and sites (r)

$$G(r,k,x,s) = A + B(r) + C(r,k) + D(r,k,x) + E(r,k,x,s)$$
 $\uparrow \qquad \uparrow \qquad \uparrow \qquad \uparrow$ 
 $level \quad site \quad attenuation \quad directivity \quad slip complexity \quad effect \quad effect \quad effect$ 



#### Averaging-Based Factorization

Define expectation of excitation G with respect to distribution p(q):

$$\langle G \rangle_q = \sum_{q \in Q} p(q) \ G(q)$$
 where  $\sum_{q \in Q} p(q) = 1$ 

Average G over p(q) and subtract:

- $G(r,k,x,s) \langle G(r,k,x,s) \rangle_{s}$  $\langle G(r,k,x,s) \rangle_{s} \langle G(r,k,x,s) \rangle_{s}$ conditional slip distribution p(s|k,x):
- conditional hypocenter distribution p(x|k):
- rupture distribution p(k):
- $\langle G(r,k,x,s)\rangle_{s,x,k,r}$ site distribution p(r):

$$G(r,k,x,s) = A + B(r) + C(r,k) + D(r,k,x) + E(r,k,x,s)$$
 $\uparrow \qquad \uparrow \qquad \uparrow \qquad \uparrow \qquad \uparrow$ 
 $level \quad site \quad attenuation \quad directivity \quad slip complexity \quad effect \quad effect \quad effect$ 

This averaging-based decomposition is unique and exact



#### Averaging-Based Factorization

The residuals between excitation functions of an arbitrary target model G(r, k, x, s) and an arbitrary reference model  $\tilde{G}(r, k, x, s)$  can be factorized in a similar manner,

$$G(r,k,x,s) - \tilde{G}(r,k,x,s) = g(r,k,x,s)$$
$$= a + b(r) + c(r,k) + d(r,k,x) + e(r,k,x,s)$$

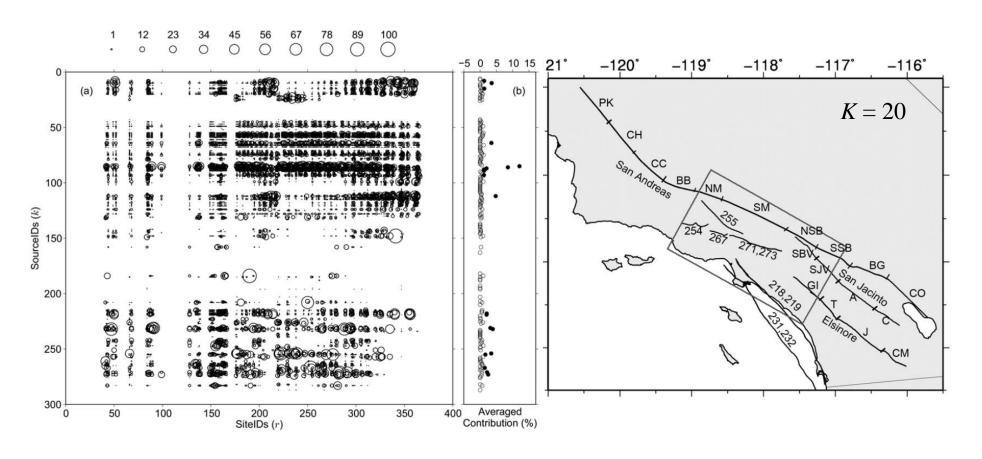
and the individual terms also average to zero:

$$\langle e(r,k,x,s)\rangle_{s} = \langle d(r,k,x)\rangle_{x} = \langle c(r,k)\rangle_{k} = \langle b(r)\rangle_{r} = 0$$

$$G(r,k,x,s) = A + B(r) + C(r,k) + D(r,k,x) + E(r,k,x,s)$$
 $\uparrow \qquad \uparrow \qquad \uparrow \qquad \uparrow \qquad \uparrow$ 
 $level \quad site \quad attenuation \quad directivity \quad slip complexity \quad effect \quad effect \quad effect$ 

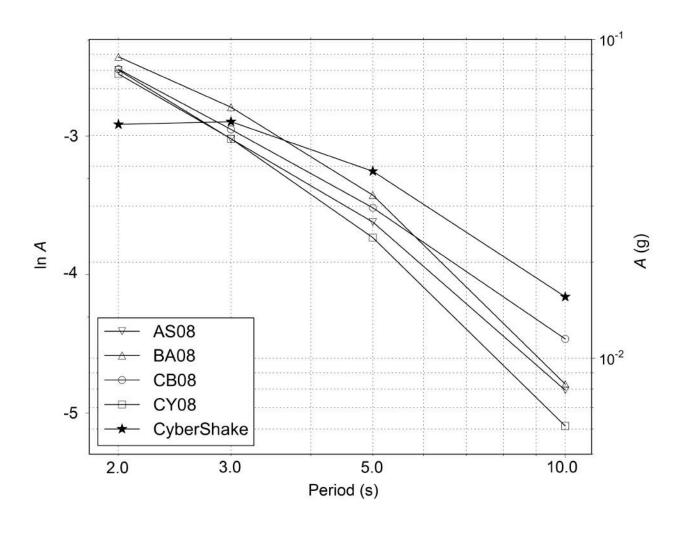


### Source Set for CyberShake ABF





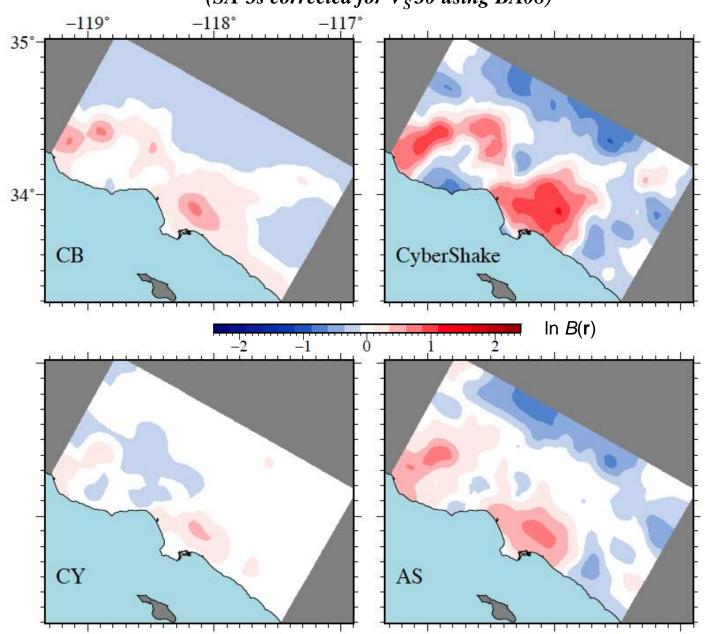
### A-values of CyberShake models





#### ABF Basin Amplification Maps

 $(SA-3s \ corrected \ for \ V_S \ 30 \ using \ BA08)$ 

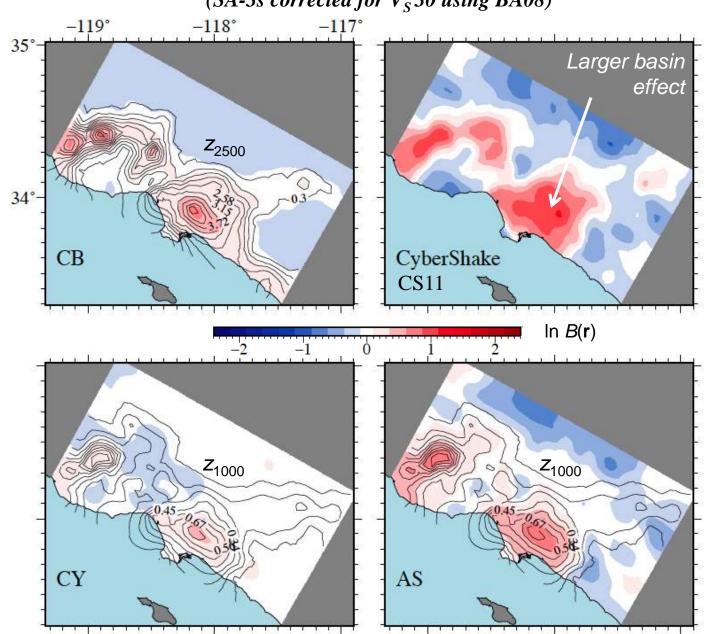


Wang & Jordan (2014)



#### ABF Basin Amplification Maps

 $(SA-3s \ corrected \ for \ V_S \ 30 \ using \ BA08)$ 

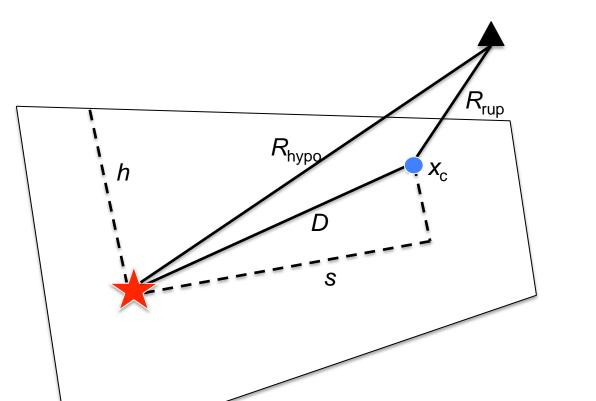


Wang & Jordan (2014)



#### Empirical Directivity Modeling

Isochrone directivity predictor (IDP) of Spudich & Chiou (2008)



$$IDP = R_{ri} \frac{\tilde{c}}{\beta} \ln(\max(s,h))$$

$$\tilde{c} = \frac{D}{T_c - T_{hypo}}$$
 isochrone velocity

$$T_{c} = \left(\frac{D}{V_{r}} + \frac{R_{rup}}{\beta}\right); T_{hypo} = \frac{R_{hypo}}{\beta}$$

$$V_r = 0.8 \beta$$

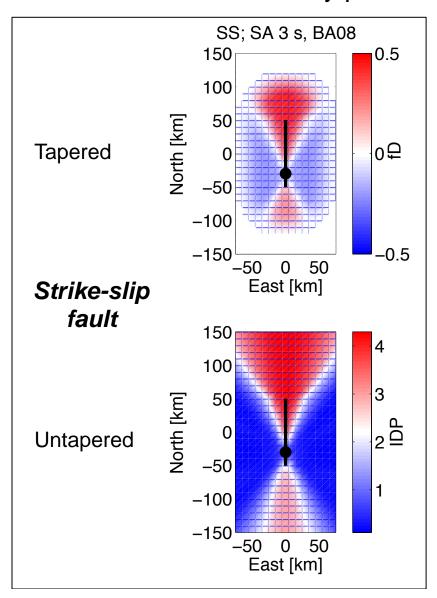
**SC08** directivity correction to the NGA GMPEs:

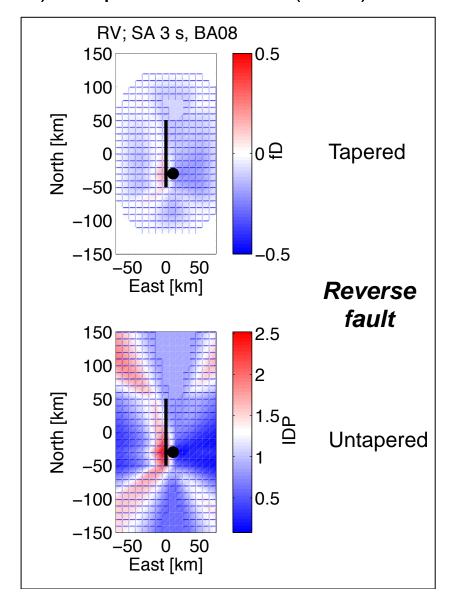
$$f_D = Taper(M, R_{rup})(a+b*IDP)$$



#### Empirical Directivity Modeling

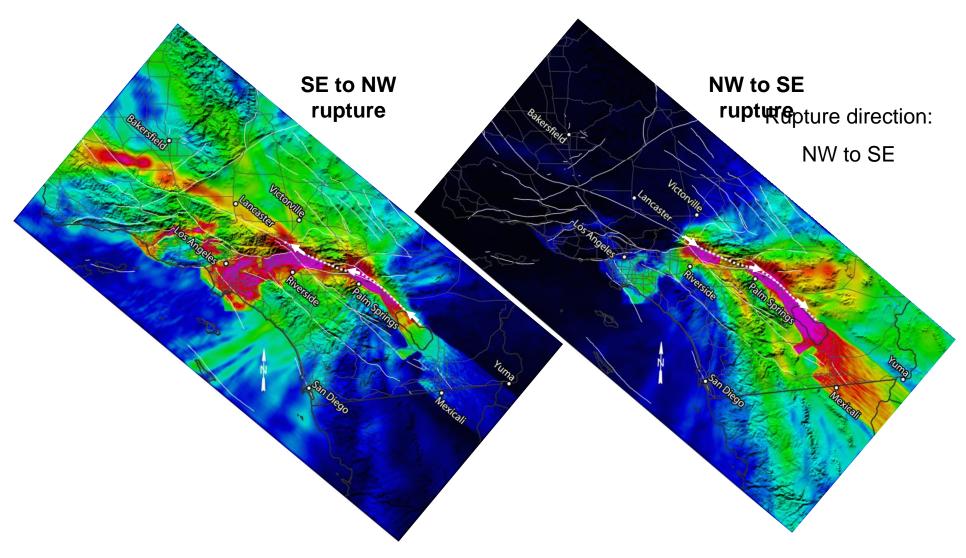
Isochrone directivity predictor (IDP) of Spudich & Chiou (2008)







### Coupling of Directivity and Basin Effects

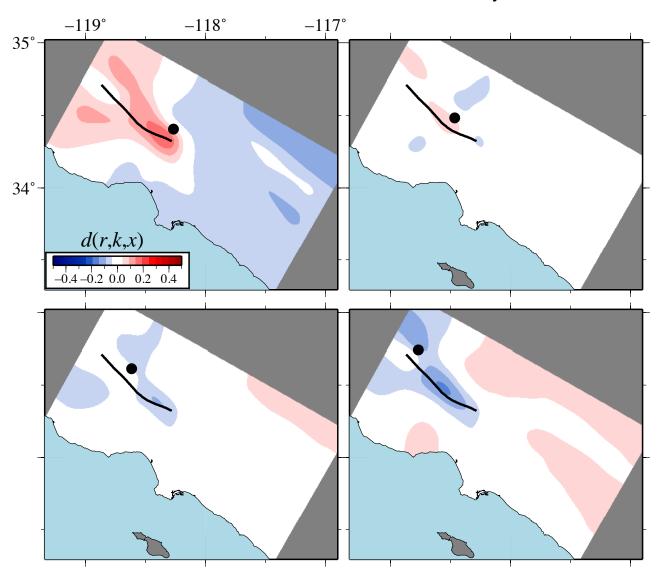


TeraShake simulations of M7.7 earthquake on Southernmost San Andreas (Olsen et al. 2006)



#### ABF Recovery of SC08 Directivity Correction

Target model: BA08 with SC08 directivity correction Reference model: BA08 without SC08 directivity correction

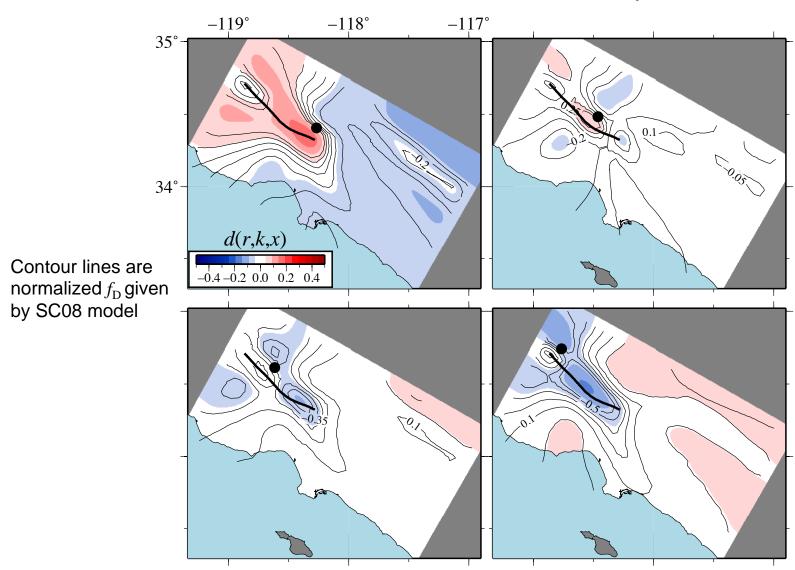


Wang & Jordan (2014)



#### ABF Recovery of SC08 Directivity Correction

Target model: BA08 with SC08 directivity correction Reference model: BA08 without SC08 directivity correction



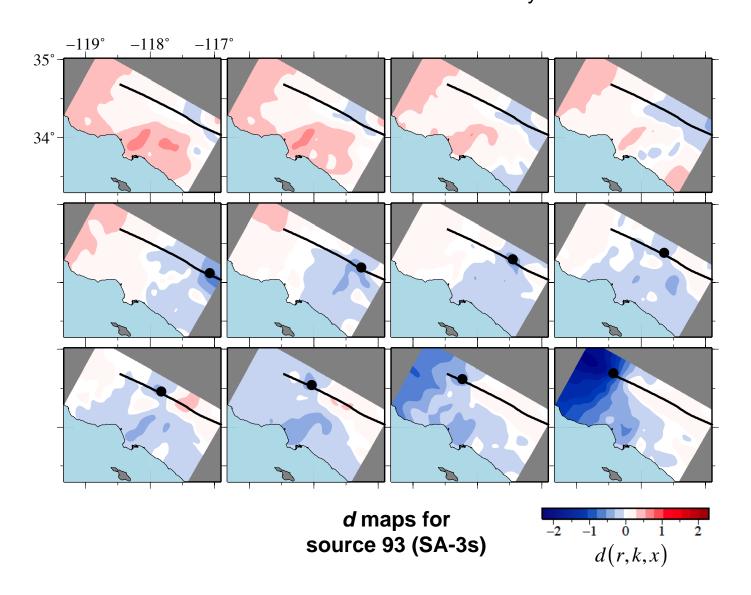
Wang & Jordan (2014)

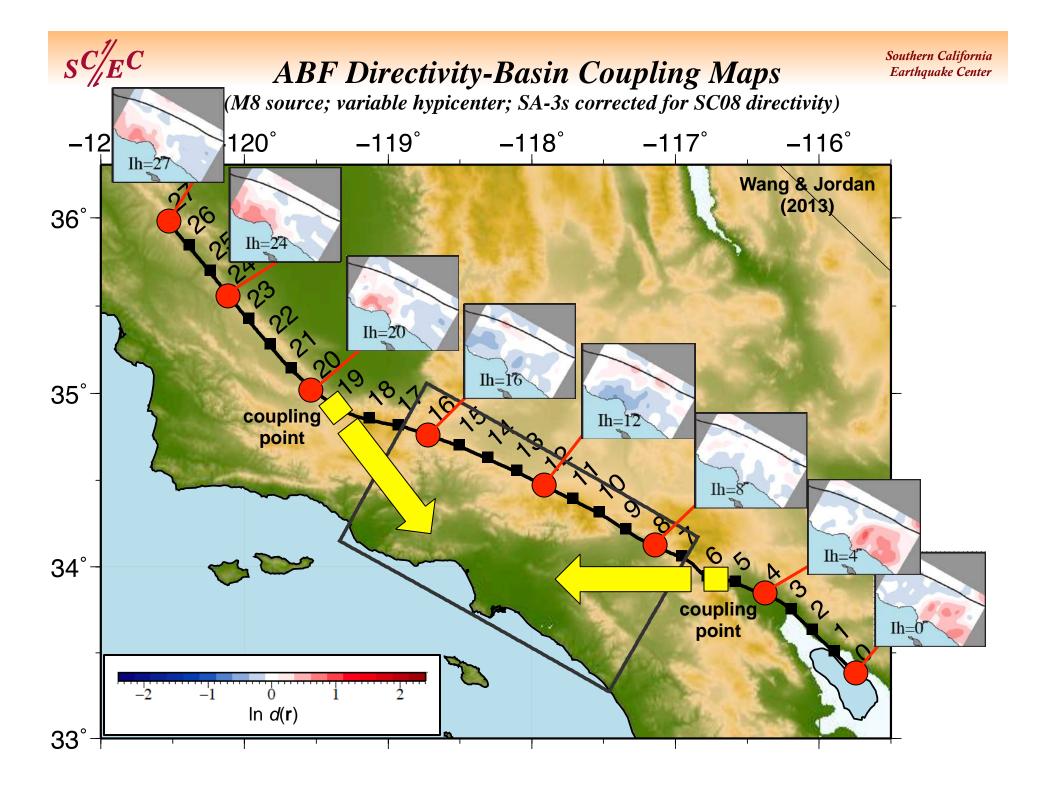


#### ABF Directivity Comparison: CS11 vs. SC08

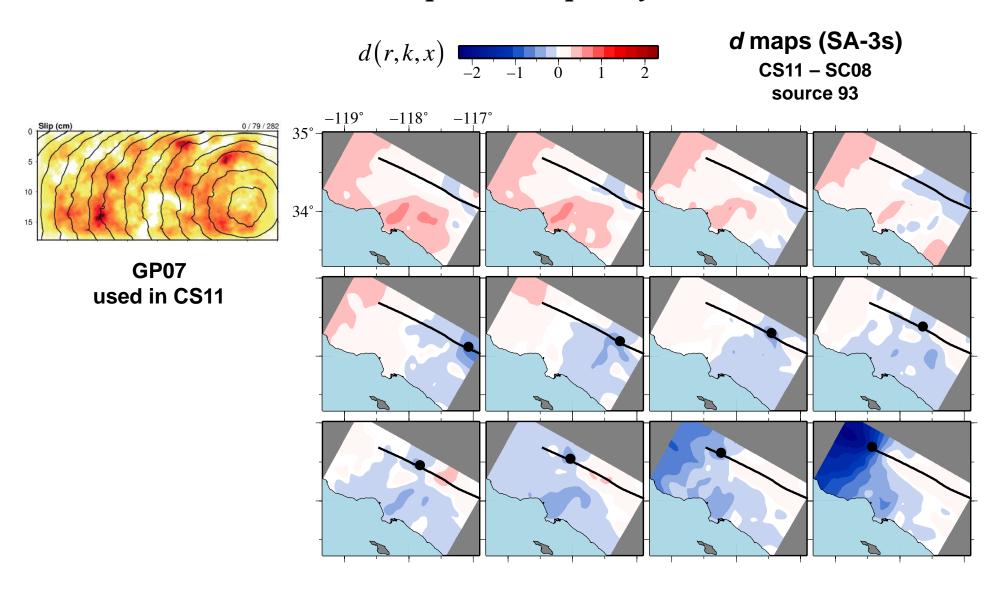
Target model: CS11 (GenSlip v2.1)

Reference model: BA08 with SC08 directivity correction

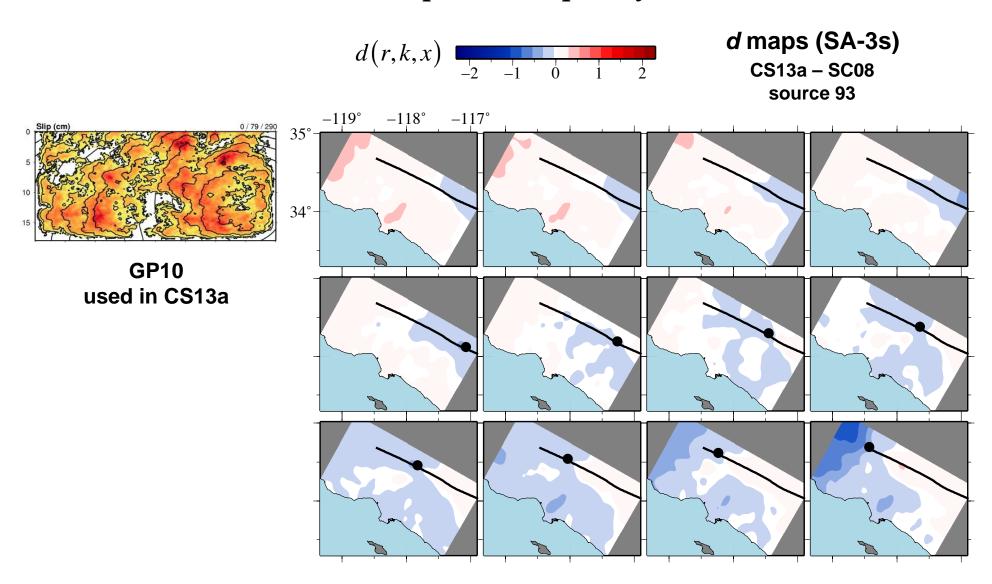




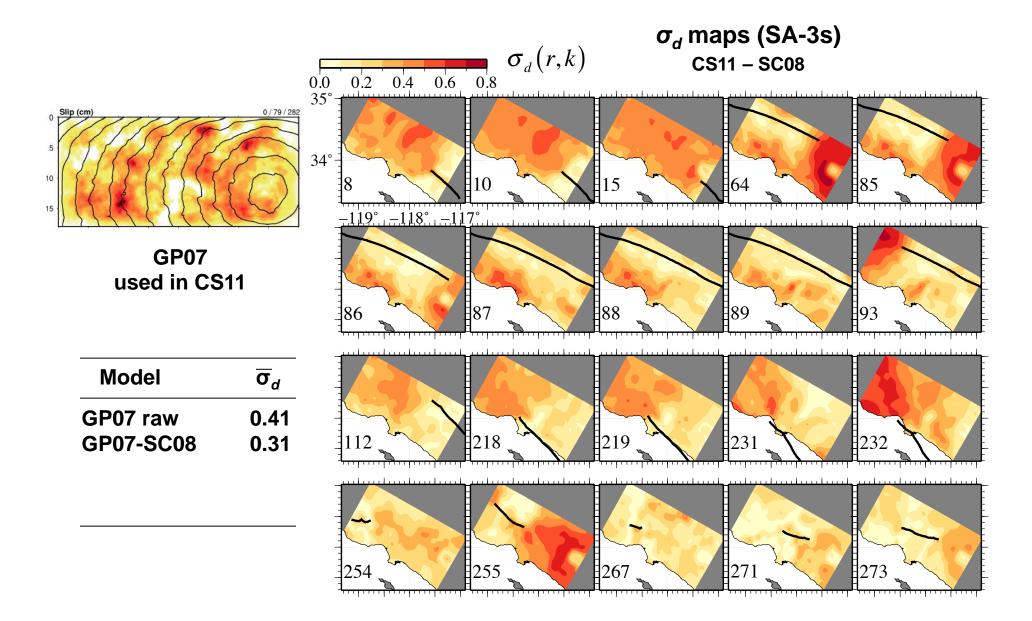




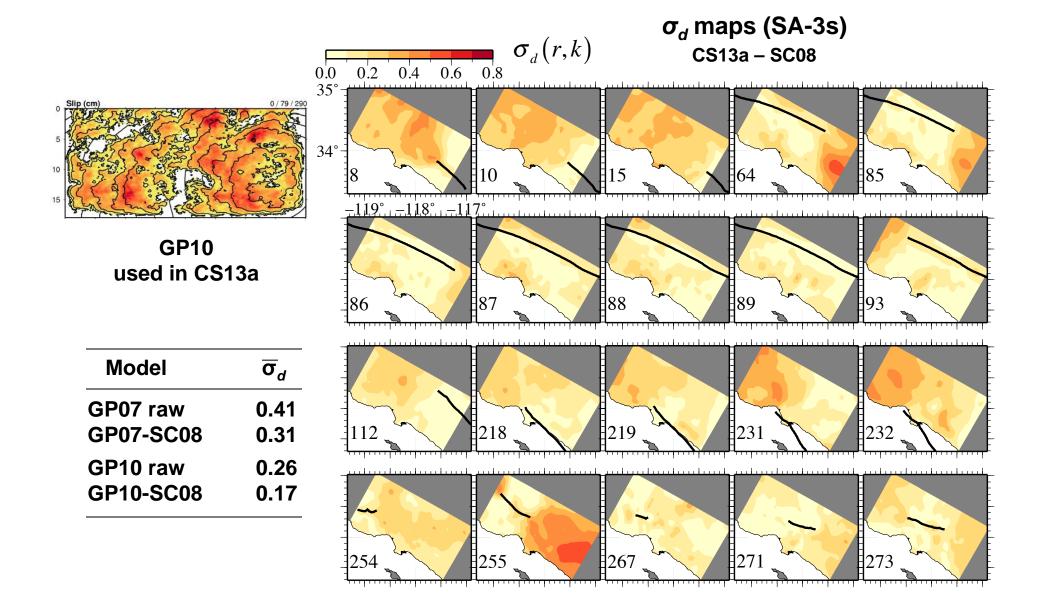






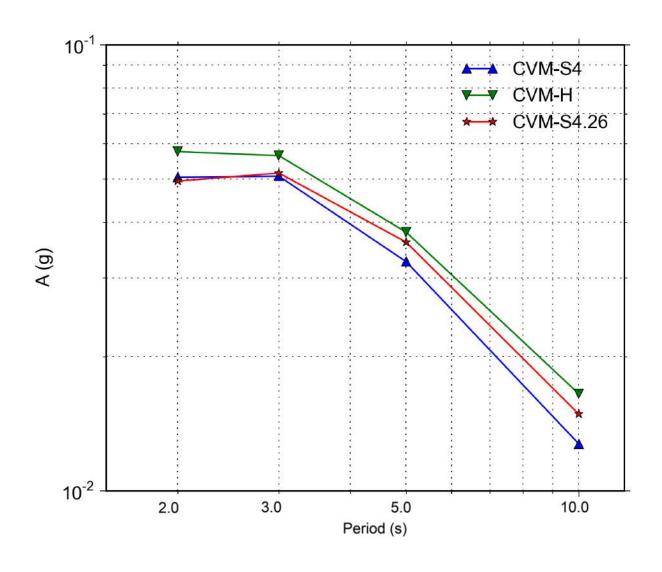








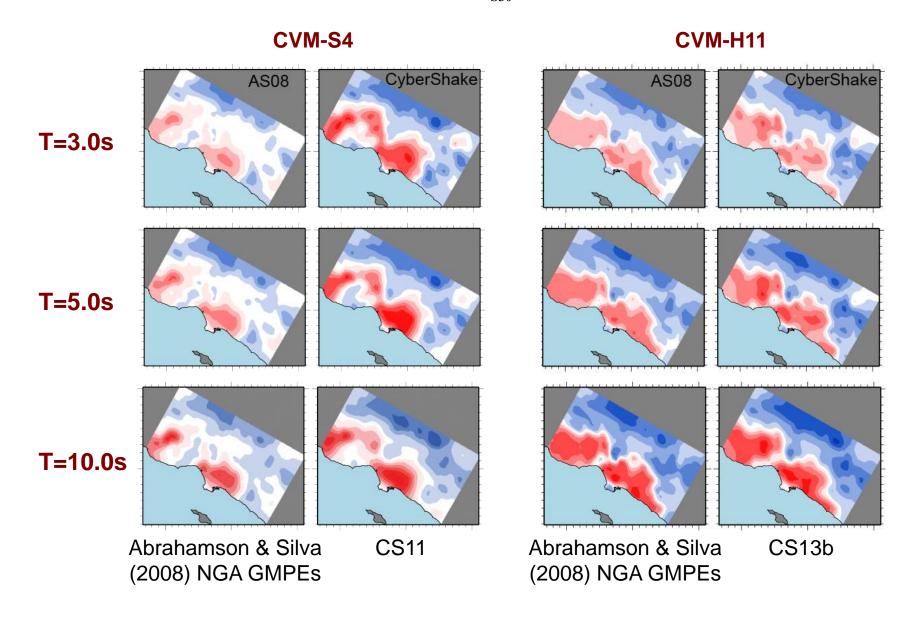
## A-values of CyberShake models





#### Dependence of Basin Effects on Velocity Structures

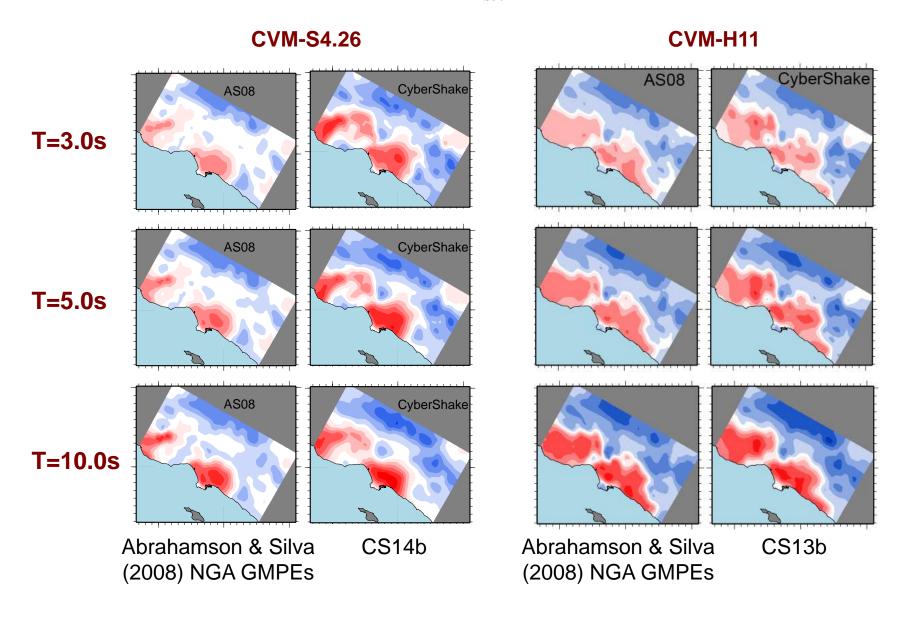
(SA corrected for  $V_{S30}$  using BA08)





#### Dependence of Basin Effects on Velocity Structures

(SA corrected for  $V_{S30}$  using BA08)

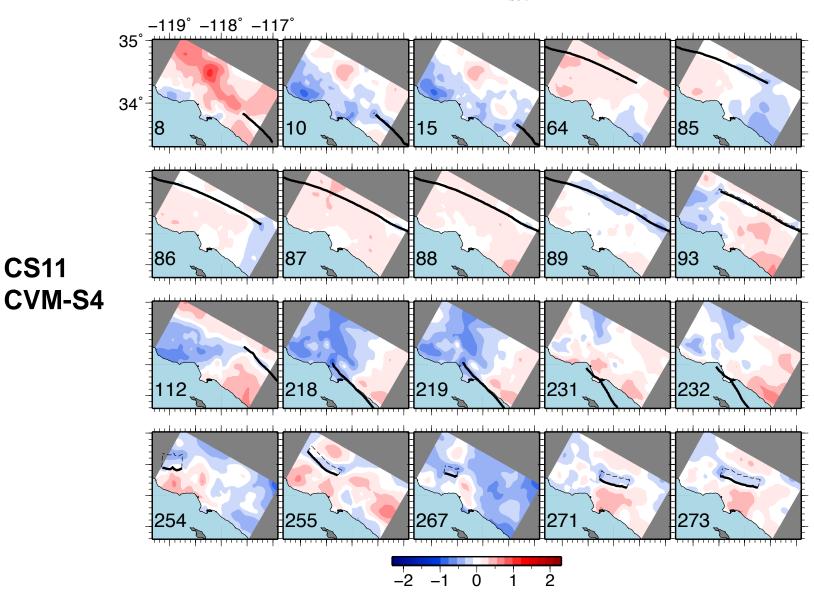




**CS11** 

#### Dependence of Path Effects on Velocity Structures

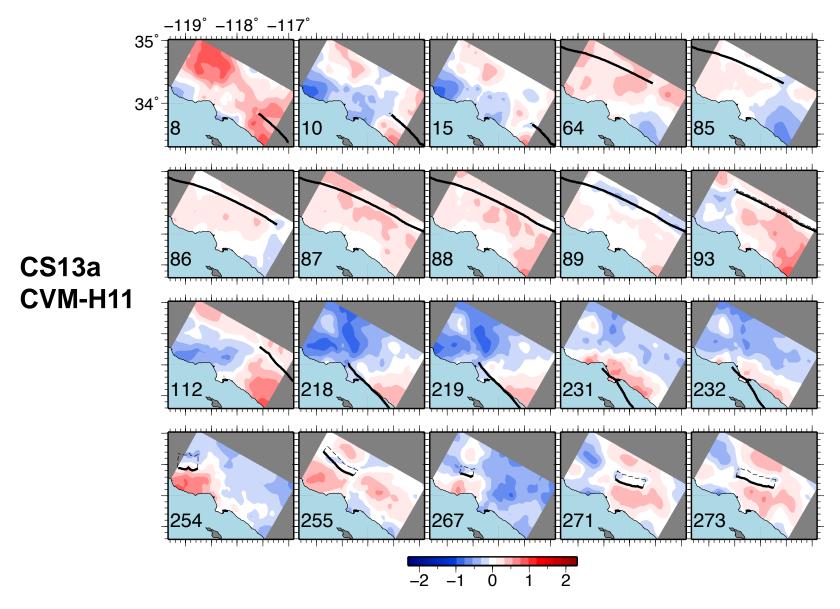
(SA-3s corrected for  $V_{S30}$  using BA08)





#### Dependence of Path Effects on Velocity Structures

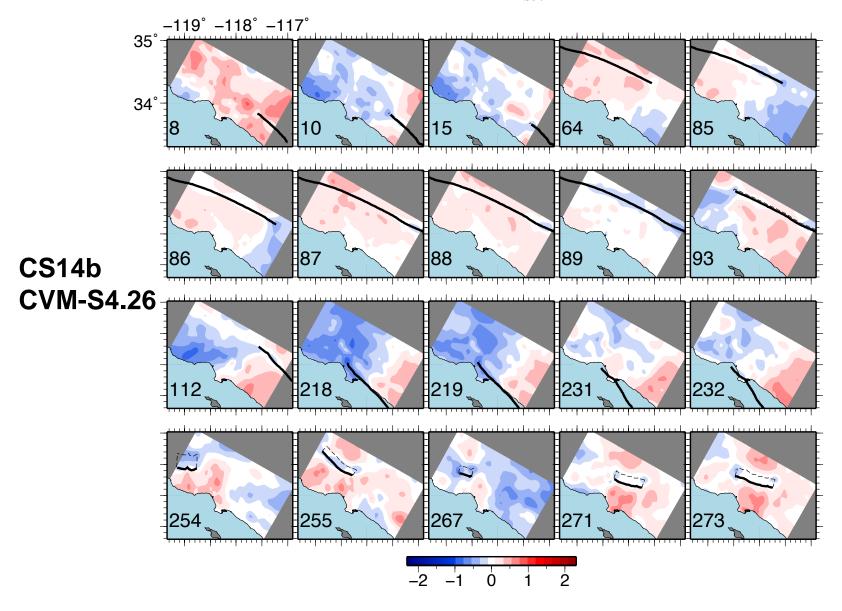
(SA-3s corrected for  $V_{S30}$  using BA08)





#### Dependence of Path Effects on Velocity Structures

(SA-3s corrected for  $V_{S30}$  using BA08)





### Averaging-Based Factorization

ABF representation of excitation functionals

$$G(r, k, x, s) = A + B(r) + C(r, k) + D(r, k, x) + E(r, k, x, s)$$

ABF representation of excitation variance

$$E[G] = \langle G(r, k, x, s) \rangle_{S,X,K,R} = A$$

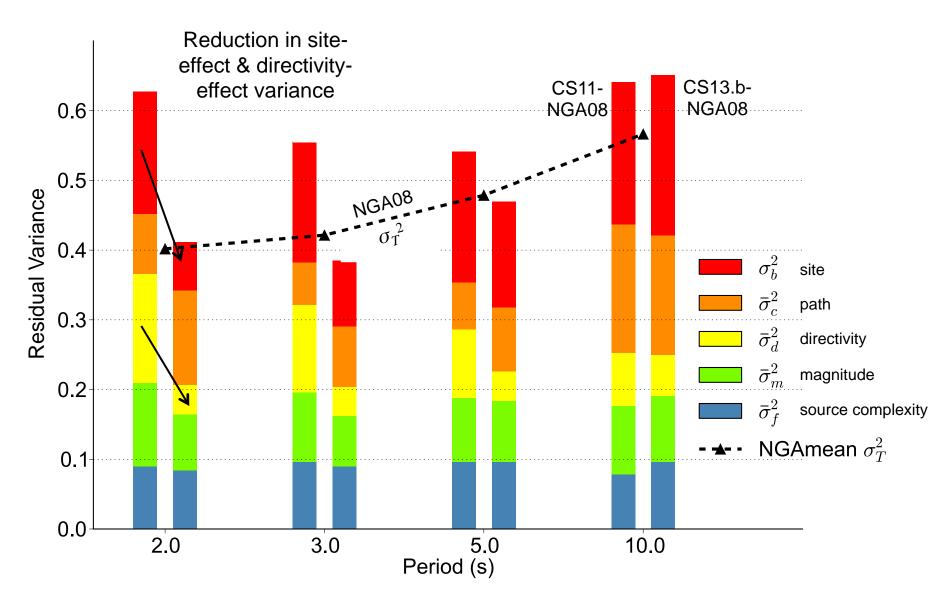
$$Var[G] = \overline{\sigma}_{G}^{2} \equiv \left\langle [G(r, k, x, s) - A]^{2} \right\rangle_{S, X, K, R}$$

$$= \sigma_{B}^{2} + \left\langle \sigma_{C}^{2}(r) \right\rangle_{R} + \left\langle \sigma_{D}^{2}(r, k) \right\rangle_{K, R} + \left\langle \sigma_{E}^{2}(r, k, x) \right\rangle_{X, K, R}$$

$$\equiv \sigma_{B}^{2} + \overline{\sigma}_{C}^{2} + \overline{\sigma}_{D}^{2} + \overline{\sigma}_{E}^{2}$$

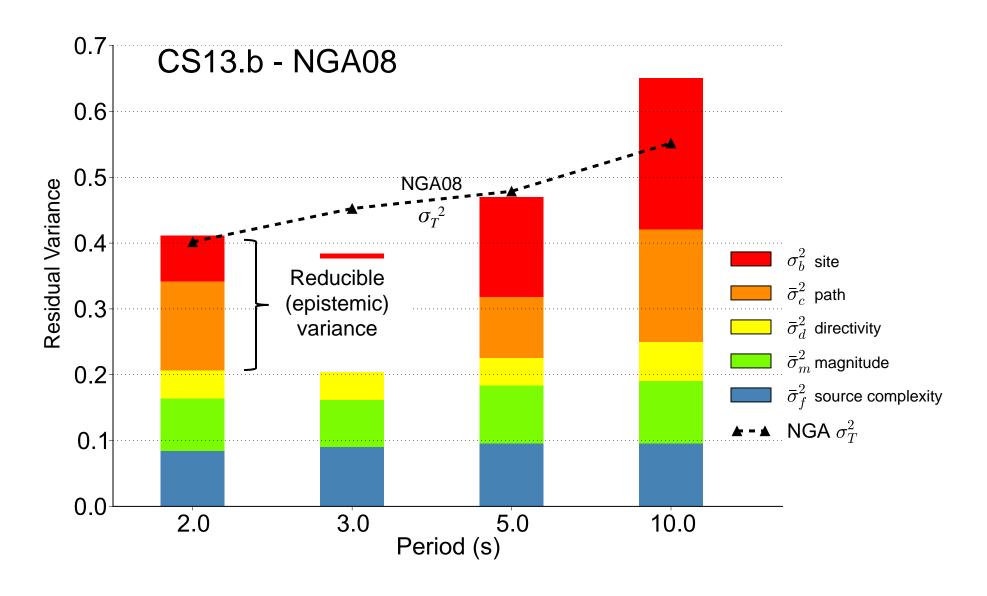


### ABF Variance Analysis



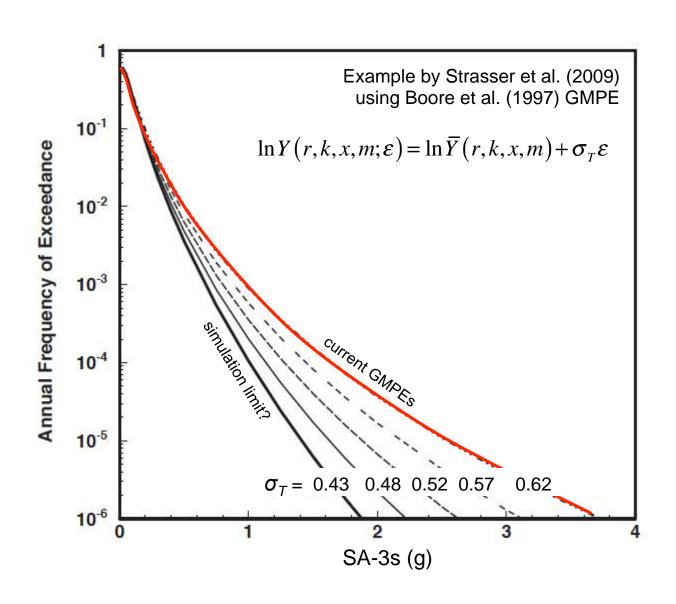


### ABF Variance Analysis





### Importance of Reducing Aleatory Variability



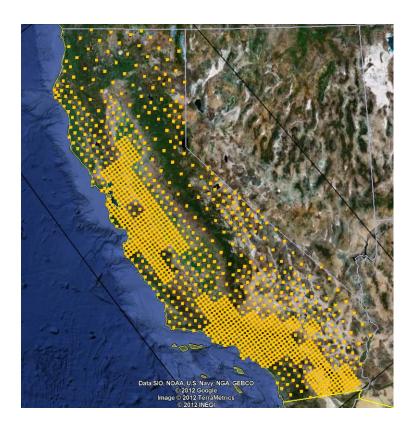


### Plans for CyberShake Research

Southern California Earthquake Center

### SC/EC CyberShake: Initiative to Compute a Statewide Physics-Based Hazard Model

- Extend CyberShake models to 1400 sites across California
  - Develop statewide Unified Community Velocity Model (UCVM)
  - Compute site response to 1 Hz deterministic, 10 Hz stochastic
- Couple time-dependent UCERF3 to **CyberShake** 
  - Provide frequently updated time-dependent seismic hazard maps
- Extend CSEP to prospectively test ground motion forecasts against observations throughout California



#### Statewide CyberShake

- Computational requirements for 1 Hz deterministic, 10 Hz stochastic:
  - Number of jobs: 23.2 billion
  - Storage: 2800 TB seismograms
  - Computer hours: 392 million



### CyberShake Science Challenges

#### Move towards

- higher frequencies (0.5 Hz → 5 Hz)
- more ruptures (UCERF3)
- more sites (1440 for statewide)

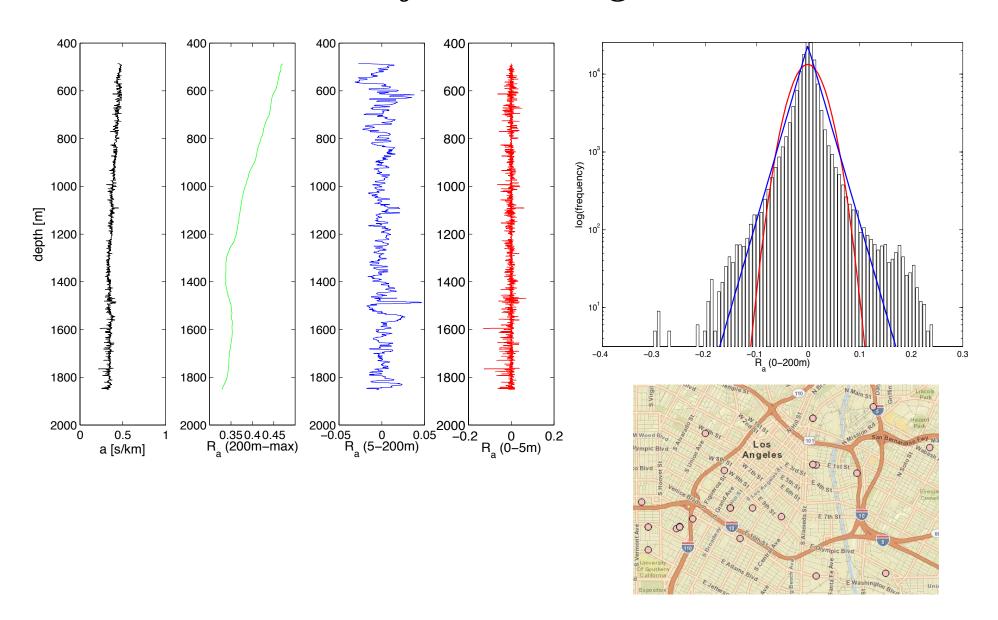
### This will require better physics...

- Frequency-dependent attenuation
- Fault roughness
- Near-fault plasticity
- Soil nonlinearities
- Near-surface heterogeneities

### ... and much more computation!



### Near-Surface Heterogeneities

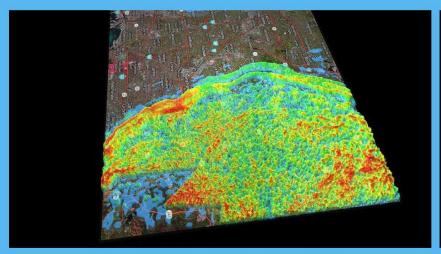




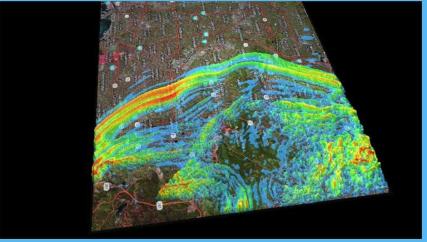
### Effects of Near-Surface Heterogeneities

### Simulated Wave Propagation for the Mw5.4 Chino Hills, CA, Earthquake, Including a Statistical Model of Small-Scale Heterogeneities

t=10 sec



**NCAR** 



For the two simulations shown, all differences can be attributed to the impact of the geological structural models.

The animation on the right shows a Chino Hills simulation with unmodified SCEC Community Velocity Model (CVM-S v11.2).

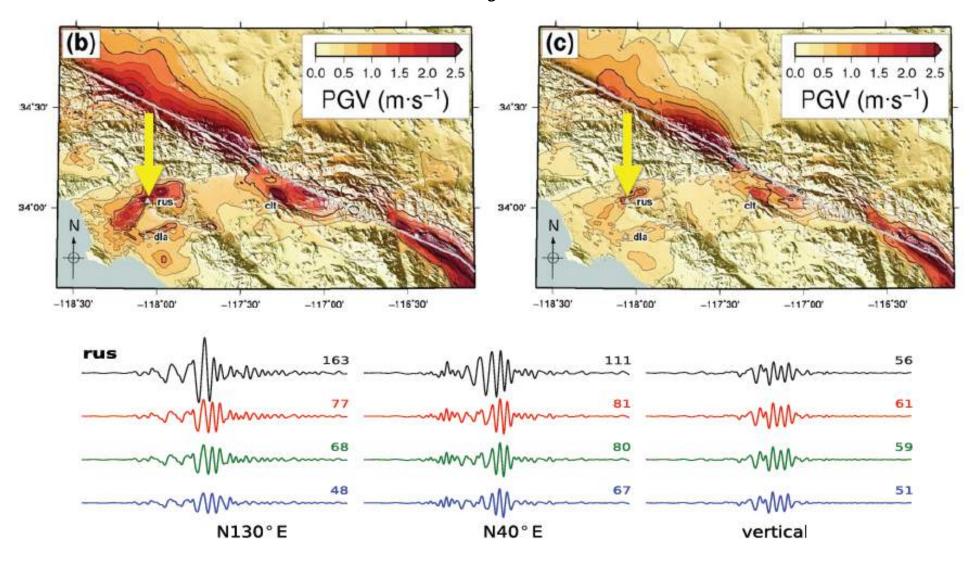
The animation on the left shows a Chino Hills simulation that uses a modified version of CVM-S v11.2 that contains more realistic small-scale complexities. The animations show that the more complex velocity structure used in the left simulation, clearly impacts that ground motion distribution, the levels of peak ground motion, and the duration of shaking. The next scientific step is to compare both simulation results against observed data for this event to determine which velocity model most closely reproduces the observed ground motions for this earthquake.



First results on SCEC's High-F project from Yellowstone



### Nonlinear Simulations of the ShakeOut Scenario



**Roten et al. (2014)** 



### Issues for the UGMS Committee

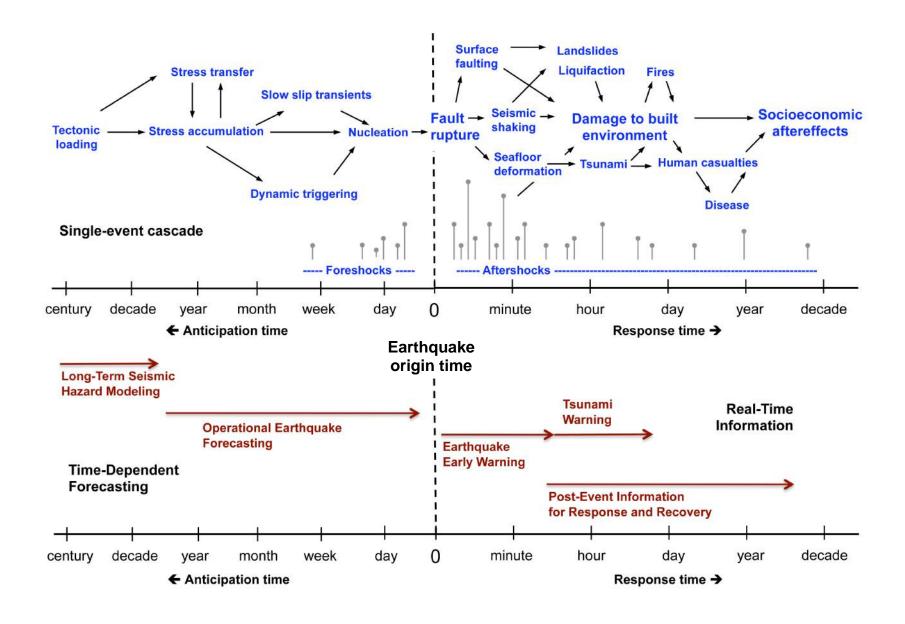
- What frequency range should CyberShake strive towards?
- How useful would be a hybrid (deterministic/stochastic) broadband CyberShake?
- What frequencies should be sampled in the CyberShake database?
- Should we compute vertical component seismograms for CyberShake?
- What performance measures should we use in validating our simulations?



### Time-Dependent Ground Motion Forecasting using CyberShake

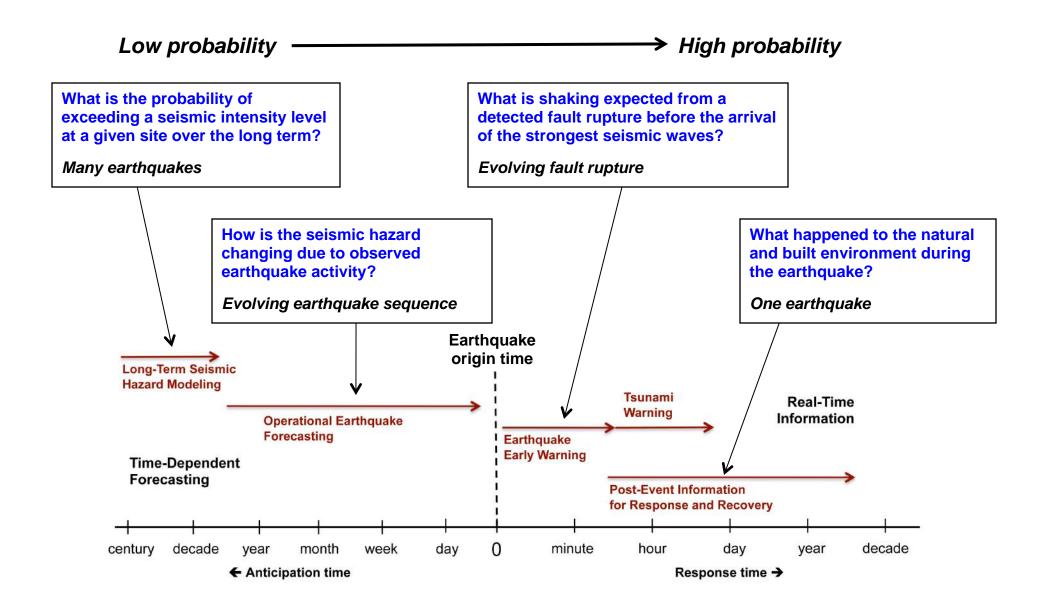


### Tracking Earthquake Cascades





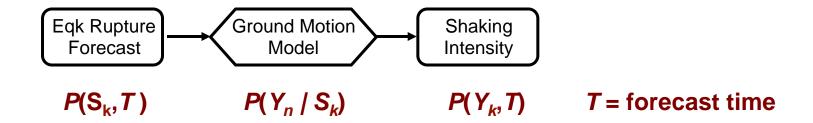
### Tracking Earthquake Cascades





## CyberShake: Application to Short-Term Earthquake Forecasting

- Pre-computed CyberShake ground motion models are easily coupled to short-term forecasting models, such as STEP and UCERF3
  - Output is a time-dependent seismic hazard estimate

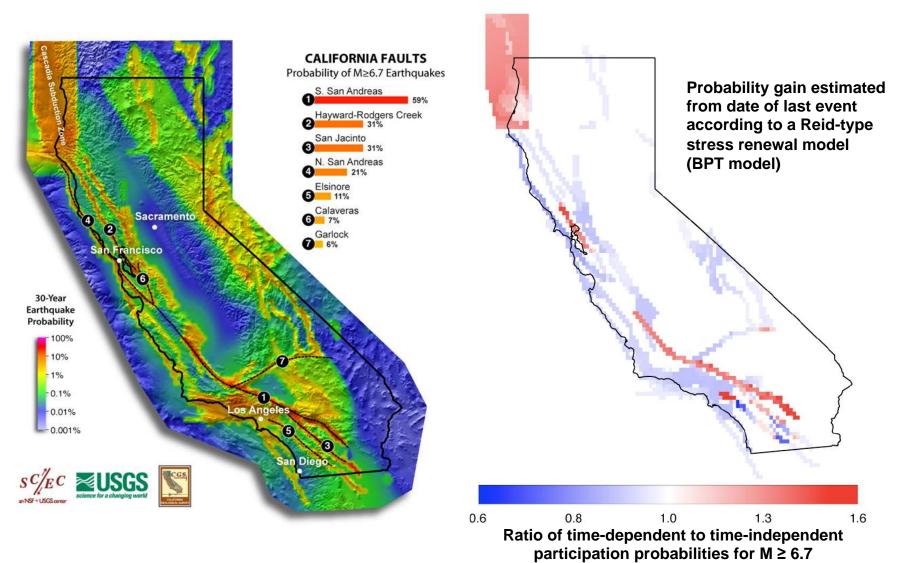


- Short-term forecasting localizes epicenter probabilities
  - Coupled model achieves significant gains in ground motion probabilities through the forecasting of source directivity and directivity-basin coupling

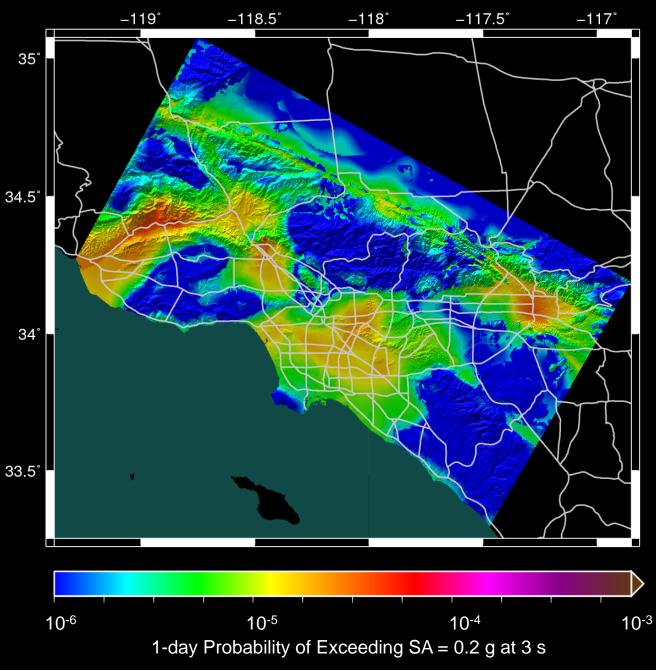


#### Working Group on California Earthquake Probabilities (2007)

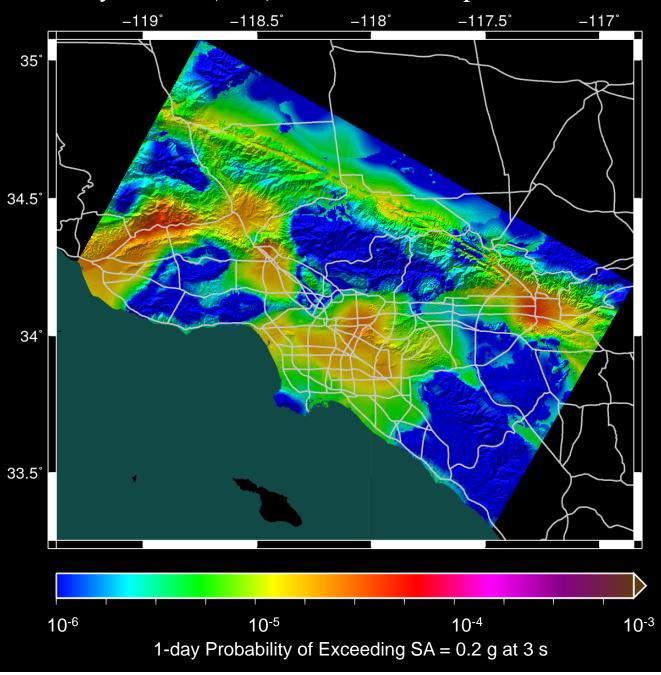
### Uniform California Earthquake Rupture Forecast (UCERF2)



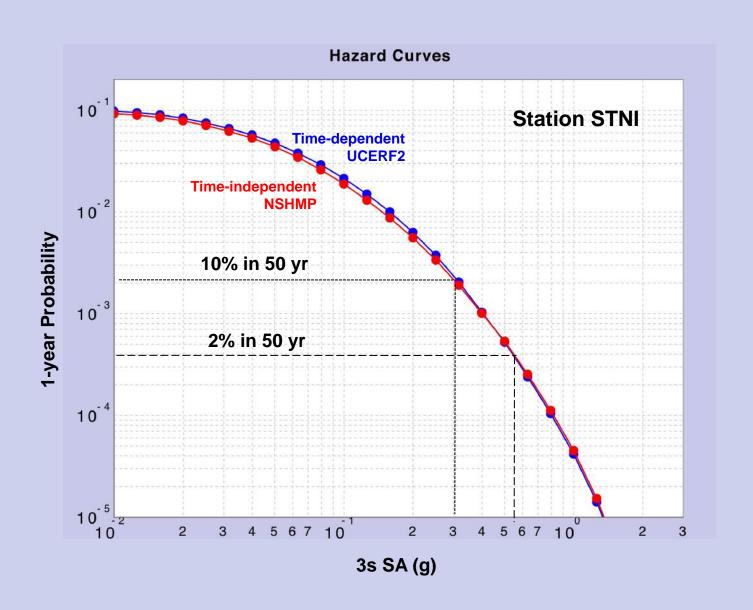
#### CyberShake (2011) NSHMP Time-Independent Model



#### CyberShake (2011) UCERF2 Time-Dependent Model

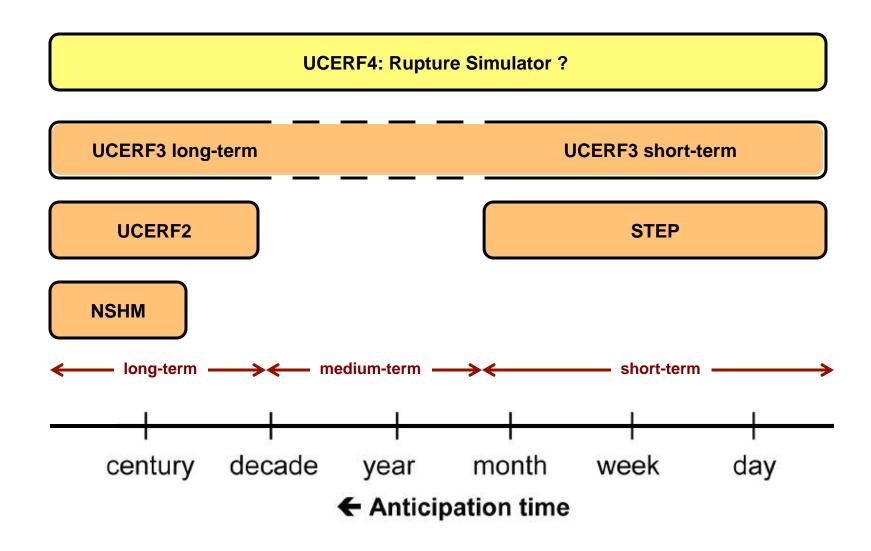


### CyberShake Time-Independent Hazard Curves



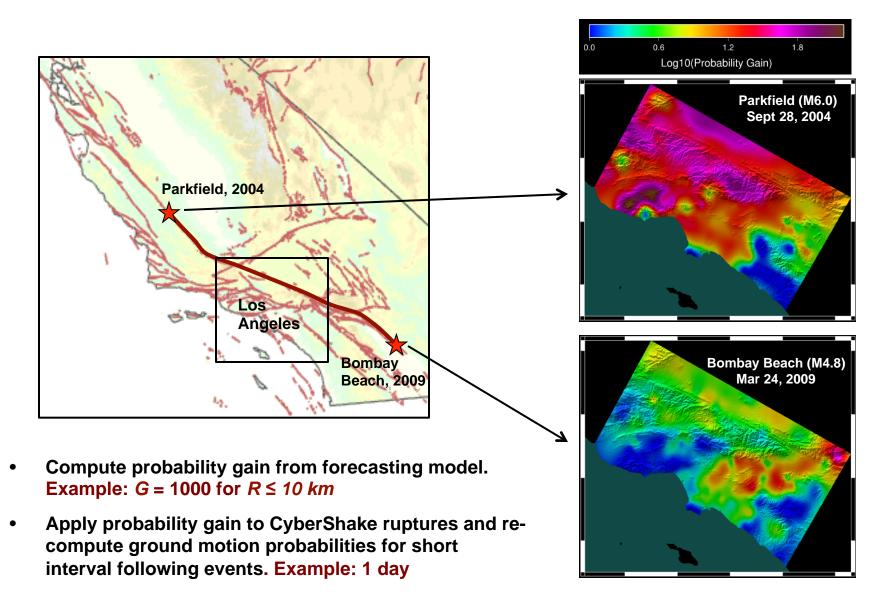


### California Earthquake Forecasting Models

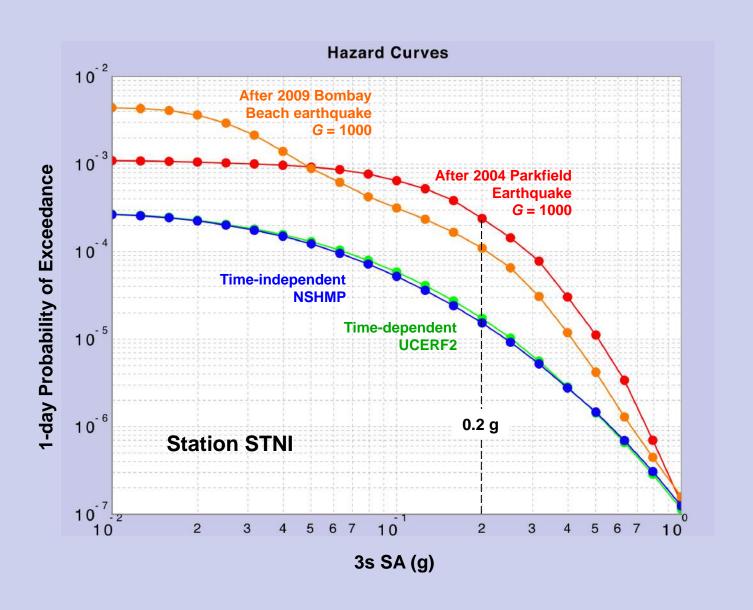




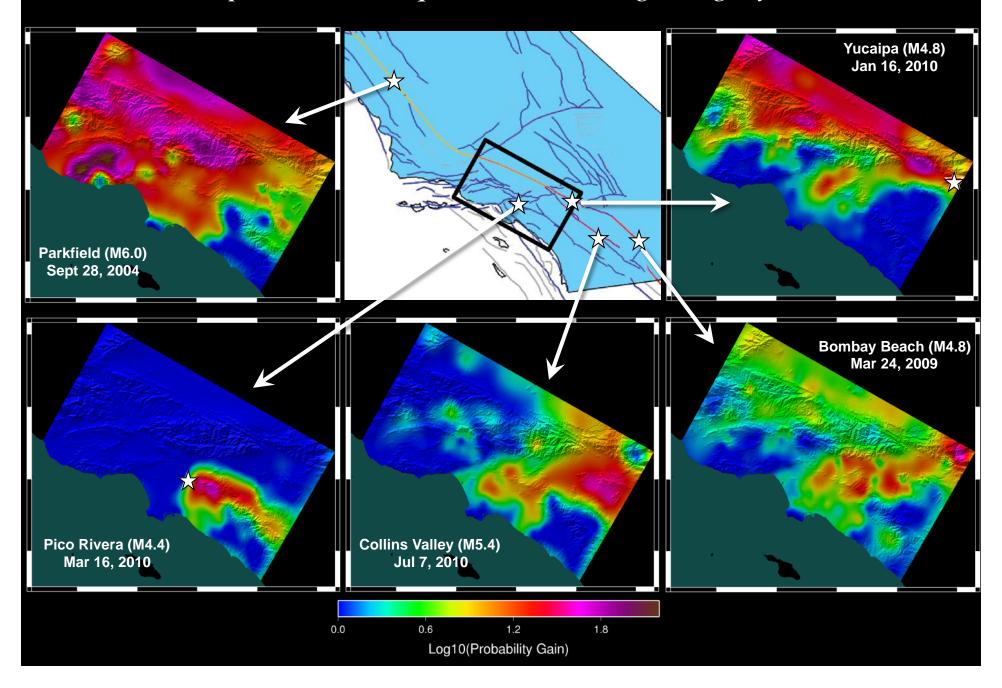
# CyberShake: Application to Short-Term Earthquake Forecasting



### CyberShake Time-Dependent Hazard Curves



### Time-Dependent Earthquake Forecasting using CyberShake





## Thank you!