

# 2018 SCEC Annual Report

## SDSU BBP Module Extension: Temporal-Spatial Ground Motion Correlation

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## Summary

Ground motion simulations can be viable alternatives to empirical relations for seismic hazard analysis when data are sparse. However, in many cases, simulated ground motion time series, in particular those originating from stochastic methods, lack inter-frequency correlation revealed in recorded seismic data, which has implications for seismic risk. We develop a post-processing method to rectify simulation techniques that otherwise produce synthetic time histories deficient in inter-frequency correlation structure.

## Fourier Amplitude Spectrum (FAS) and Effective Amplitude Spectrum (EAS)

The Effective Amplitude Spectrum (EAS), defined by Kottke *et al.* (2018) as

$$EAS(f) = \sqrt{\frac{1}{2}[FAS_{HC1}^2(f) + FAS_{HC2}^2(f)]}, \quad \text{Eq. 1}$$

is used as the intensity measure in our study. In Eq. 1,  $FAS_{HC1}$  and  $FAS_{HC2}$  are the FAS of the two as-recorded horizontal components of a three component acceleration time series, and  $f$  is the frequency in Hertz. The  $EAS$  is independent of the recording instrument's orientation. The  $EAS$  is smoothed using the  $\log_{10}$ -scale Konno and Ohmachi (1998) smoothing window selected by Kottke *et al.* (2018):

$$W(f) = \left( \frac{\sin(b \log(f/f_c))}{b \log(f/f_c)} \right)^4, \quad \text{Eq. 2}$$

$$b = \frac{2\pi}{b_w}, \quad \text{Eq. 3}$$

where  $W$  is the weight defined at frequency  $f$  for a window with center frequency  $f_c$ ,  $b$  is the window parameter, and  $b_w = \frac{1}{30}$  is the bandwidth of the smoothing window in  $\log_{10}$  units. For more details on the smoothing technique, the reader is referred to Kottke *et al.* (2018).

## Inter-Frequency Correlations of Within-Event Residuals

We follow the notation defined by Al Atik *et al.* (2010):

$$y_{es} = \mu_{es} + \delta B_e + \delta W_{es}, \quad \text{Eq. 4}$$

where  $y_{es}$  is the natural logarithm of the ground-motion intensity measure observed at station  $s$  during earthquake  $e$ , and  $\mu_{es}$  is the mean prediction of the natural logarithm of the intensity measure.  $\delta B_e$  is the between-event residual (or inter-event residual), representing the average shift of the observed ground motion for an individual earthquake  $e$  from the population mean prediction.  $\delta W_{es}$  is the within-event residual (or intra-event residual), depicting the misfit between an individual observation at station  $s$  from the earthquake-specific mean prediction. The source effect average (over all azimuths) is described by the between-event residual that reflects the influence of factors such as stress drop and variation of slip in time and space that cannot be captured by the inclusion of magnitude, faulting style, and source depth in the mean prediction. Azimuthal variations in source, path, and site effects are described by the within-event residual that reflects the influence of factors such as crustal heterogeneity, deeper geological structure, and near-surface layering that cannot be captured by a simple distance metric and a site-classification based on the average shear-wave velocity (Al Atik, et al., 2010). These residuals are normally distributed with zero mean and are uncorrelated with each other.

In this study, we target the EAS within-event residual through epsilon ( $\varepsilon$ ),

$$\varepsilon(f) = \frac{\delta W_{es}(f)}{\varphi(f)} = \frac{\ln EAS_{es}(f) - \mu_{\ln EAS_{es}}(f) - \delta B_e}{\varphi(f)}, \quad \text{Eq. 5}$$

the within-event residual normalized by its standard deviation  $\varphi$ . The value of the within-event residual of EAS depends on frequency  $f$ . By the normalization, epsilon is standard normally distributed with zero mean and unit standard deviation.

For a given set of observations, the values of  $\varepsilon$  at neighboring frequencies ( $f$ ) are probabilistically correlated. If a ground motion intensity measure is stronger than average at a certain frequency, then it tends to also be stronger at nearby frequencies; however, the  $\varepsilon$  values are weakly correlated if the frequency pair are widely-separated (Bayless and Abrahamson, 2018b). The correlation coefficient of  $\varepsilon$  at two frequencies  $f_1$  and  $f_2$  can be estimated by the maximum likelihood estimator (Kutner *et al.*, 2004) using the Pearson product-moment correlation coefficient (Fisher, 1958),

$$\rho_{\varepsilon(f_1)\varepsilon(f_2)} = \frac{\sum_{i=1}^n (\varepsilon_i(f_1) - \overline{\varepsilon(f_1)}) (\varepsilon_i(f_2) - \overline{\varepsilon(f_2)})}{\sqrt{\sum_{i=1}^n (\varepsilon_i(f_1) - \overline{\varepsilon(f_1)})^2} \sqrt{\sum_{i=1}^n (\varepsilon_i(f_2) - \overline{\varepsilon(f_2)})^2}}, \quad \text{Eq. 6}$$

in which  $n$  is the number of observations,  $\varepsilon_i(f_1)$  and  $\varepsilon_i(f_2)$  represent the  $i$ th observation of  $\varepsilon$  at frequencies  $f_1$  and  $f_2$ , respectively,  $\overline{\varepsilon(f_1)}$  and  $\overline{\varepsilon(f_2)}$  are their sample means, and the expectations of  $\varepsilon(f_1)$  and  $\varepsilon(f_2)$  are both zero. This correlation is important when simulated time histories are used for seismic risk analysis because variability in the dynamic structural response will be underestimated if the inter-frequency correlation in simulated ground motions is unrealistically low (Bayless and Abrahamson, 2018b).

Bayless and Abrahamson (2018a) generated an empirical estimate of  $\rho$  for the EAS within-event residual using the NGA-West2 database (regression from shallow crustal earthquakes, with  $M > 3$ ) at frequencies from 0.1 Hz to 24 Hz. The epsilon at each frequency was calculated from the individual EAS values and the earthquake-specific smoothed EAS median model for each recorded event at each station. Then,  $\rho_{\varepsilon(f_1)\varepsilon(f_2)}$  was calculated for each pair of frequencies,  $f_1$  and  $f_2$ . Figure 1 shows the empirical correlation coefficients.

### Inclusion of Inter-frequency Correlation in FAS

The procedure to generate a new ground motion time series with realistic inter-frequency correlations is as follows:

- (1) take the Fourier transform of the two horizontal components of the synthetic ground motion time series. For each component, let the number of frequency points be  $n$ , the Fourier amplitude and phase at the  $i$ th frequency be  $Amp_{ori}(i)$  and  $Ph_{ori}(i)$ , respectively;
- (2) for each of the horizontal components, sample a normally distributed vector-valued random variable  $R$  with zero mean, a constant standard deviation,  $\sigma$ , and size  $n$ ;
- (3) express the empirical covariance  $\rho_{\varepsilon(f_1)\varepsilon(f_2)}$  from Eq. 6 in matrix form  $\Sigma$  ( $n$  by  $n$ , real, symmetric, and positive definite), and apply the Cholesky decomposition of  $\Sigma$  as

$$\Sigma = \mathbf{K}\mathbf{K}^T, \quad \text{Eq. 7}$$

where  $\mathbf{K}$  is a  $n$  by  $n$  lower triangular matrix (Seydel, 2012);  
 (4) left multiply random variable  $R$  in (3) by  $\mathbf{K}$  as

$$\mathbf{S} = \mathbf{K}\mathbf{R}, \quad \text{Eq. 8}$$

to generate a normal random variable  $S$  with zero mean and covariance equal to  $\sigma^2 \mathbf{K}\mathbf{K}^T = \sigma^2 \Sigma$  (Seber and Lee, 2012);

(5) multiply the exponential of  $S$  with  $Amp_{ori}$  to compute the Fourier amplitude of the new ground motion synthetics,  $Amp_{new}$ , as

$$Amp_{new}(i) = Amp_{ori}(i) \exp S_i; \quad \text{Eq. 9}$$

(6) calculate the new ground-motion time series by applying the inverse Fourier transform to the spectrum obtained in (5).

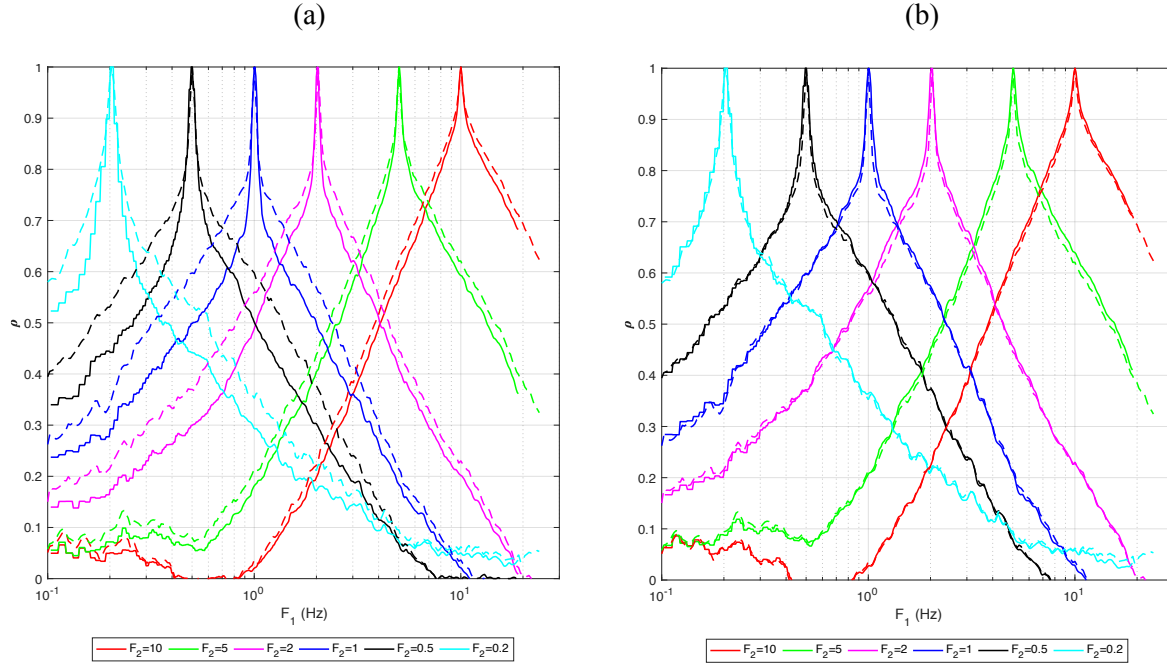
The method can be applied as the last step to simulate the ground-motion using the SDSU SCEC BBP module, and thus classified as post-processing. It retains the mean of the Fourier amplitude for the updated ground-motion synthetics, since the mean of  $\exp S_i$  in step (5) equals 1. Taking the natural logarithm of the equation in step (5) we get

$$\ln Amp_{new}(i) = \ln Amp_{ori}(i) + S_i. \quad \text{Eq. 10}$$

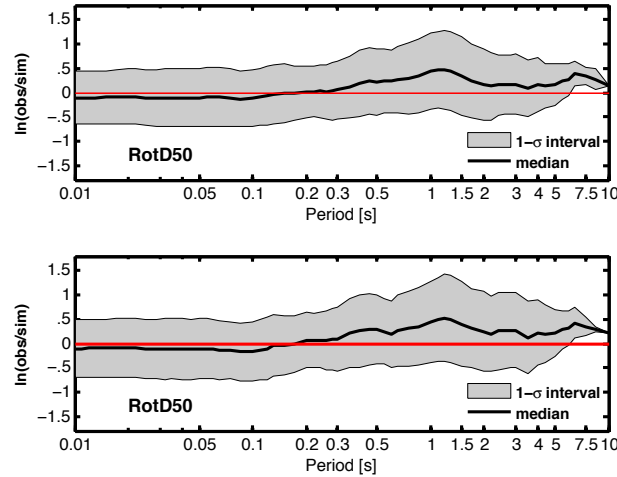
We tested our method by calculating the within-event residual for the Loma Prieta event on the SCEC BBP. It is important to emphasize that the results generated using different source realizations from the kinematic source generator module by Graves and Pitarka (2015) for that validation event should be treated as different events, rather than multiple realizations of the same event. The reason for this is that the source realizations have variations in hypocenter locations and slip distributions that are represented by the between-event residual. Then, for each event, we generate 10 realizations at all the stations from each of the 50 ‘events’ by changing the seed number in the random number generator for the scatterograms. For each set of 10 realizations, the mean of the 10 simulations and the within-event residual at each station are computed. The within-event residual at all stations and all realizations of the ‘events’ are pooled together by their corresponding frequency. Note, that if the total number of stations is  $m$ , then at each frequency  $f$  the epsilon of the within-event residual  $\epsilon(f)$  has a size equal to 10 realizations by 50 ‘events’ by  $m = 500m$ .

Figure 1 shows that the resulting inter-frequency correlation coefficients obtained by our method for the Loma Prieta validation event compare very well with the empirical result, as intended. From Figure 2 it is clear that the addition of correlation to the synthetic time histories results in insignificant changes in the bias. The method generates correlated synthetic time series that are very similar to the original results from current SDSU BBP Module. Figure 3 shows one component of synthetic time histories (velocity and acceleration) and FAS, respectively, at station 8001-CLS for the Loma Prieta validation event before and after implementing the inter-frequency correlations. The method can be used as a post-processing step to incorporate the correlation into

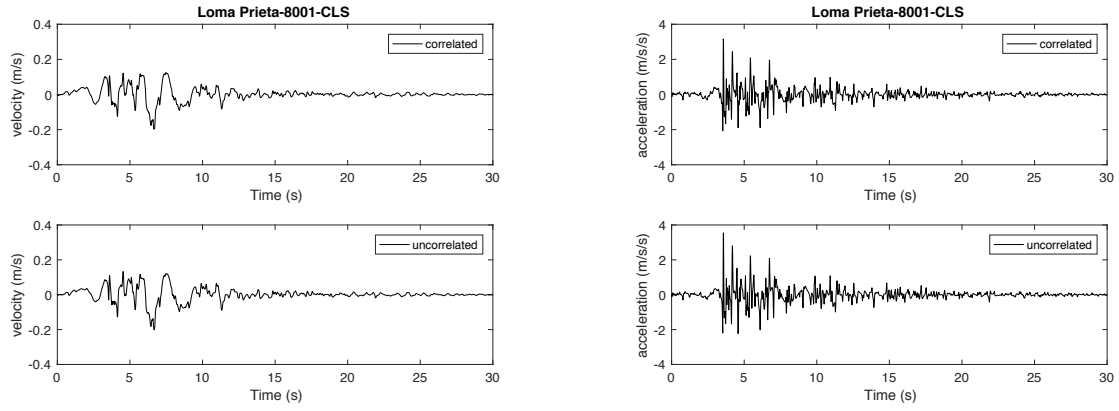
an already established and validated ground motion generator. Finally, Figure 4 shows that our method also works well to incorporate realistic inter-frequency correlation into PSA.



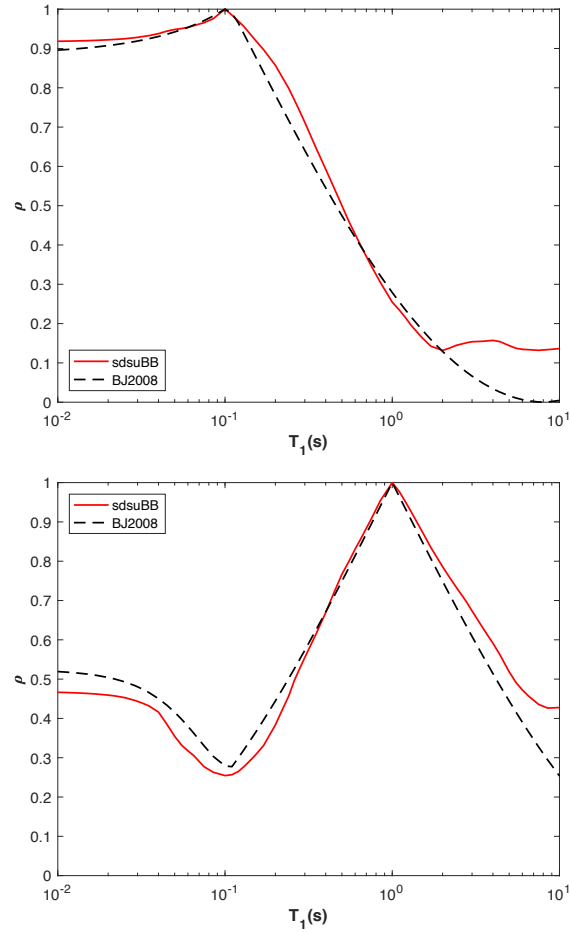
**Figure 1.** The inter-frequency correlation coefficients of epsilon at reference frequencies 0.2 Hz, 0.5 Hz, 1 Hz, 2 Hz, 5 Hz and 10 Hz from the empirical correlation coefficients (dashed lines) and the SDSU SCEC BBP Module after applying our method. (a) Using independent random variables at two horizontal components (solid lines), and (b) using correlated random variables (with correlation coefficient equals 0.7) at two horizontal components (solid lines) for the Loma Prieta event.



**Figure 2.** The natural log of the misfit between median RotD50 PSA for observations and predictions using 50 source realizations for the original (uncorrelated) (top) and (bottom) correlated SDSU synthetics for the Loma Prieta event.



**Figure 3.** Examples of the north-south component of velocities (left) and accelerations (right) at station 8001-CLS for Loma Prieta event after (top) and before (bottom) implementing the inter-frequency correlations.



**Figure 4.** Comparison of the inter-frequency spectral acceleration correlation coefficients of epsilon at reference periods 0.1 s (top) and 1 s (bottom) from the Baker and Jayaram (2008) model (dashed black lines) and the SDSU SCEC BBP Module after applying our method (solid red lines) for the Loma Prieta event with 50 realizations.

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